Finite Element Solution of Poroelastoplasticity in Strain-softening Porous Media

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Outline

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Background

• Laboratory triaxial compression experiment of geomaterials

• Strain-softening phenomenon is very common in Petroleum Geomechanics



FEM for elasto-plastic consolidation

• Field equations

$$G\nabla^{2}\boldsymbol{u} + (G+\lambda)\nabla di\boldsymbol{v}(\boldsymbol{u}) - \left(1 - \frac{K}{K_{m}}\right)\nabla p = 0$$
$$\left(1 - \frac{K}{K_{m}}\right)di\boldsymbol{v}(\boldsymbol{u}_{t}) + \left[\frac{1 - \emptyset}{K_{m}} + \frac{\emptyset}{K_{f}} - \frac{1}{(3K_{m})^{2}}i^{T}Di\right]p_{t} + \frac{k}{\mu}\nabla^{2}p = 0$$

Galerkin discretization

$$\begin{bmatrix} \boldsymbol{M} & -\boldsymbol{C} \\ \boldsymbol{0} & \boldsymbol{H} \end{bmatrix} \begin{bmatrix} \boldsymbol{u} \\ \boldsymbol{p} \end{bmatrix} + \begin{bmatrix} \boldsymbol{0} & \boldsymbol{0} \\ \boldsymbol{C}^T & \boldsymbol{S} \end{bmatrix} \begin{bmatrix} \boldsymbol{u}_t \\ \boldsymbol{p}_t \end{bmatrix} = \begin{bmatrix} \boldsymbol{f}^u \\ \boldsymbol{f}^p \end{bmatrix}$$

• Time discretization

$$\begin{bmatrix} \theta \mathbf{M} & -\theta \mathbf{C} \\ \mathbf{C}^T & \mathbf{S} + \theta \Delta t \mathbf{H} \end{bmatrix} \begin{bmatrix} \mathbf{u}_{n+1} \\ \mathbf{p}_{n+1} \end{bmatrix} = \begin{bmatrix} (\theta - 1) \mathbf{M} & -(\theta - 1) \mathbf{C} \\ \mathbf{C}^T & \mathbf{S} + (\theta - 1) \Delta t \mathbf{H} \end{bmatrix} \begin{bmatrix} \mathbf{u}_n \\ \mathbf{p}_n \end{bmatrix} + \begin{bmatrix} \mathbf{f}^u \\ \Delta t \mathbf{f}^p \end{bmatrix}$$

FEM for elasto-plastic consolidation

• Initial stress method

$$\begin{bmatrix} \theta \mathbf{M} & -\theta \mathbf{C} \\ \mathbf{C}^T & \mathbf{S} + \theta \Delta t \mathbf{H} \end{bmatrix} \begin{bmatrix} \mathbf{u}_{n+1} \\ \mathbf{p}_{n+1} \end{bmatrix} = \begin{bmatrix} (\theta - 1)\mathbf{M} & -(\theta - 1)\mathbf{C} \\ \mathbf{C}^T & \mathbf{S} + (\theta - 1)\Delta t \mathbf{H} \end{bmatrix} \begin{bmatrix} \mathbf{u}_n \\ \mathbf{p}_n \end{bmatrix} + \begin{bmatrix} \mathbf{f}^u \\ \Delta t \mathbf{f}^p \end{bmatrix} + \begin{bmatrix} \mathbf{R} \\ \mathbf{0} \end{bmatrix}$$

• Numerical flow chart



Strain-softening process

• Stress changes in brittle-plastic plasticity



Diagram of stress-dropping

Brittle-plastic model

Simplification of strain-softening process



Strain-softening process

• Stress changes in M-C

Assumption: constant minor principal stress

Peak stress surface: $F_p(\sigma_{1p}, \sigma_{3p}, \eta) = \sigma_{1p} - \alpha_p \sigma_{3p} - Y_p = 0$ Residual stress surface: $F_r(\sigma_{1r}, \sigma_{3r}, \eta) = \sigma_{1r} - \alpha_r \sigma_{3r} - Y_r = 0$

$$\Delta \sigma_3 = \sigma_{3r} - \sigma_{3p} = 0$$
$$\Delta \sigma_1 = \sigma_{1r} - \sigma_{1p} = (\alpha_r - \alpha_p)\sigma_{3r} + Y_r - Y_p$$

Assume the ratio of difference of the principal stress is constant

$$\Delta \sigma_2 = \sigma_{2r} - \sigma_{2p} = \sigma_{3r} + \frac{\sigma_{2p} - \sigma_{3p}}{\sigma_{1p} - \sigma_{3p}} (\sigma_{1r} - \sigma_{3r}) - \sigma_{2p}$$

Strain-softening process

• Evolution of strength parameters

• Plastic shear strain $(\eta = \varepsilon_1^p - \varepsilon_3^p)$

is chosen to measure strength parameters



$$w(\eta) = \begin{cases} w_p - (w_p - w_r)(\eta/\eta^*) & 0 < \eta < \eta^* \\ w_r & \eta > \eta^* \end{cases}$$

Numerical results

Consolidation considering strain-softening



Half width of footing, $a(m)$	10
Young's modulus, $E(Mpa)$	2
Poisson's ratio, ν	0.3
η^*	0.06
$c_p(Mpa)$	0.01
$c_r({ m Mpa})$	0.006
$\varphi_p(\text{deg})$	20
$\varphi_r(\text{deg})$	14
$\psi(ext{deg})$	20
Permeability $k(m/day)$	10 ⁻⁵

Finite element mesh

Numerical results



Conclusions

- In coupled hydro-mechanical (H-M) system, if material exhibits strainsoftening behavior, the strain-softening model should be applied, otherwise, the results will deviate far from the real solution.
- Finite element method is capable of solving the coupled H-M problem with strain softening considered.