

Stability Analysis On Natural And Artificial Slopes Under Earthquake Loading Based On Non-Linear Material Models

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Contents

- ULS and SLS issues on stability analysis of slopes
- Pseudo static analysis with non-linear constitutive laws
- Non-linear material behaviour (attractor states, anisotropy) for cyclic loading
- Constitutive laws on cyclic behaviour of soils
- Diffraction effects on artificial slopes consisting of materials with different stiffnesses

Questions raised to ULS and SLS for natural and artificial slopes under seismic loads

Seismic effects on slopes: :

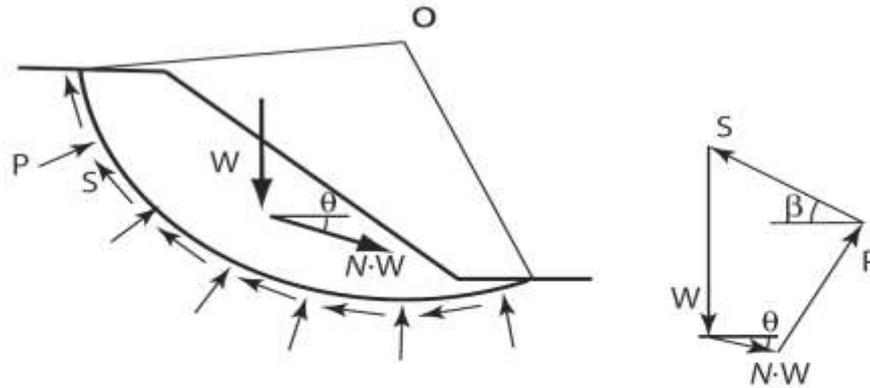
- Induction of mass acceleration on the slope stability (is the static limit analysis still possible?).
- Reduction of the shear resistance due to accumulation of pore water pressure.

$$\tau_f = c + (\sigma - u \uparrow) \tan \varphi$$

- Failure due to large deformations (**cyclic mobility**) or desintegration of the soil structure due to the degradation of the contact forces (**partial liquefaction**) leading to **instable particle system**
- **Separation of the material phases** (solid, air, water) - (phase separation, lateral spreading)

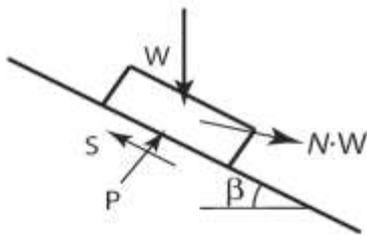


System failure of slopes

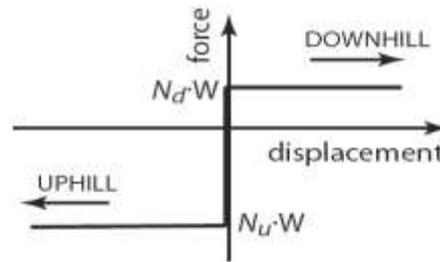


a. POTENTIAL SLIDING MASS

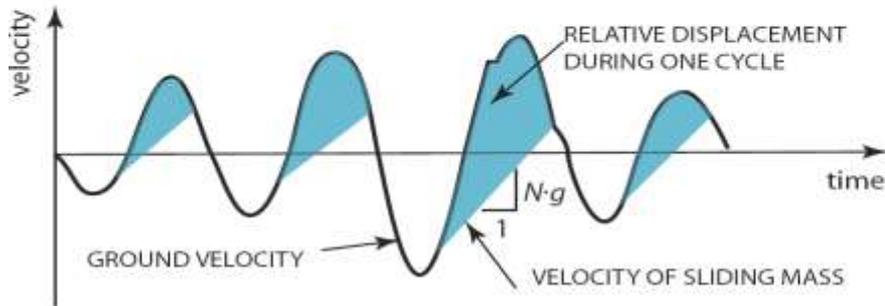
b. FORCE POLYGON FOR F.S. = 1.0



c. SLIDING BLOCK MODEL



d. FORCE-DISPLACEMENT RELATION



COMPUTATION OF DISPLACEMENT

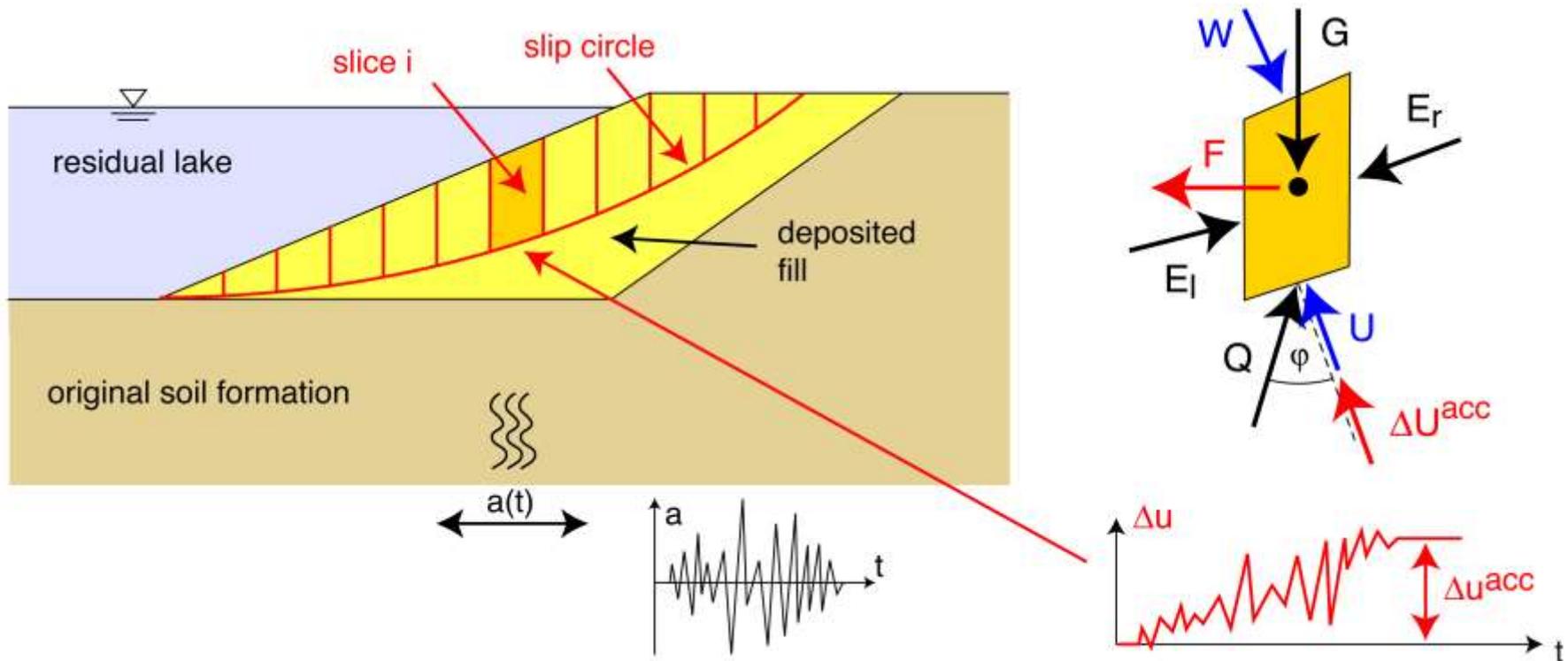
Pseudo static or dynamic analysis (without desintegration)

■ Hynes-Griffin Method (sliding block analysis NEWMARK)
 Excess of energy not absorbed by friction is transferred to block movement (kinetic energy) on the inclined plane.

How large is the allowable movement until failure occurs?
 Equilibrium states below the global FOS = 1.0 are possible (permanent deformations)

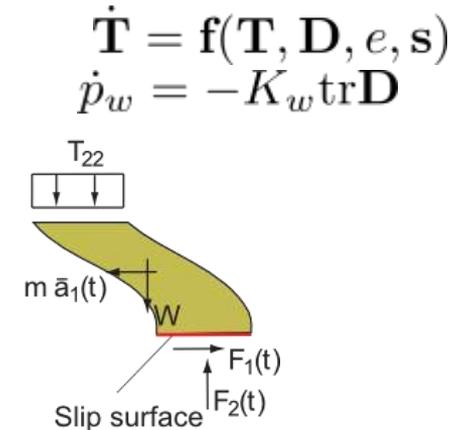
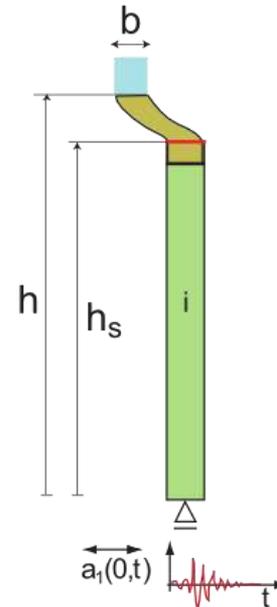
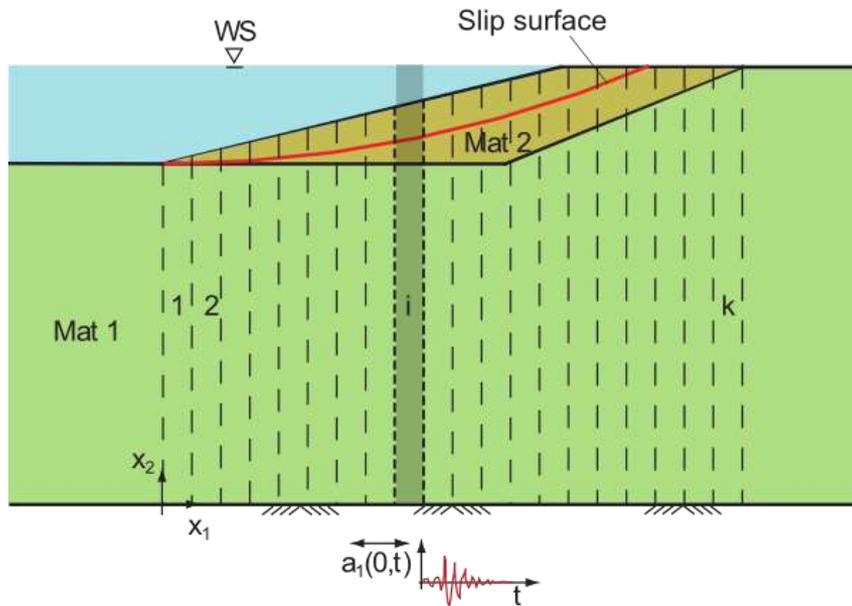
Performance based design!!

Pseudostatic analysis



- Bishop method (vertical slices)
- Inertia forces acting on the slices $\bar{F} = m\chi a_{max}$
- (m: mass, a_{max} : maximum acceleration, pseudo-static coefficient χ)

Scheme for the computation of χ from 1-d analysis



$$\dot{\mathbf{T}} = \mathbf{f}(\mathbf{T}, \mathbf{D}, e, \mathbf{s})$$

$$\dot{p}_w = -K_w \text{tr} \mathbf{D}$$

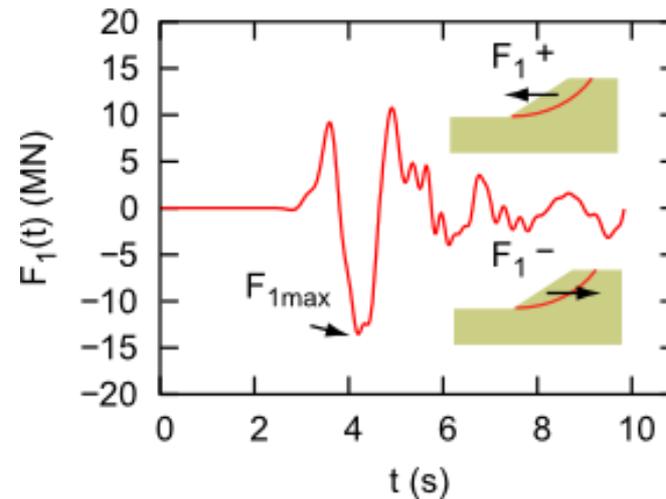
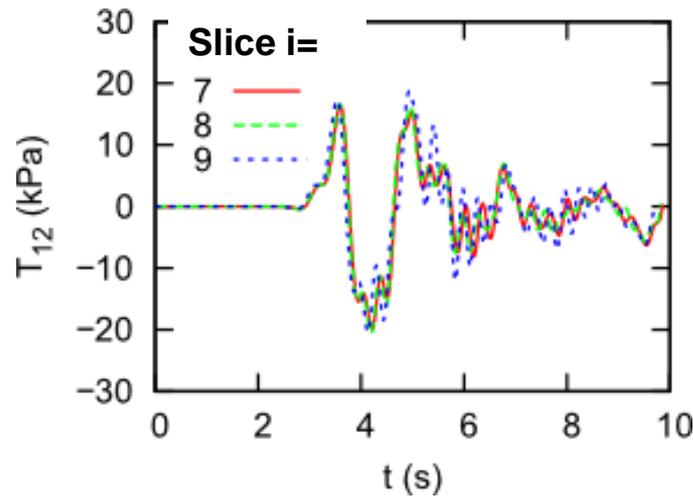
Impulse balance: $\frac{\partial T_{12}^i(x_2, t)}{\partial x_2} = \rho a_1^i(x_2, t)$

Integration from $x_2 = h_s$ to $x_2 = h$

$$F_1^i(t) = b \int_{h_s}^h \frac{\partial T_{12}^i}{\partial x_2} dx_2 = b \rho \int_{h_s}^h a_1^i dx_2 = m^i \bar{a}_1^i(t)$$

$$F_1^i(t) = b \overbrace{[T_{12}^i(h, t) - T_{12}^i(h_s, t)]}^{=0} = -b T_{12}^i(h_s, t) = m^i \bar{a}_1^i(t)$$

Scheme for the determination of χ



The forces $F_1^i(t) = b T_{12}^i(t)$ at time t will be added over the entire number k of slices

$$F_1(t) = \sum_{i=1}^k F_1^i(t) \quad \text{and from that} \quad F_{1 \max} = \max(|F_1(t)|)$$

With the mass m of the sliding body we can compute

$$\chi = \frac{F_{1 \max}}{\max(|a_1(h=0, t)|) \cdot m} \quad \text{or} \quad \chi^{PGA} = \frac{F_{1 \max}}{PGA \cdot m}$$

Material failure: Liquefaction due to cyclic loading (Deterioration of the grain skeleton structure)

Examples



Christchurch, New Zealand, 2016



Christchurch, New Zealand, 2011

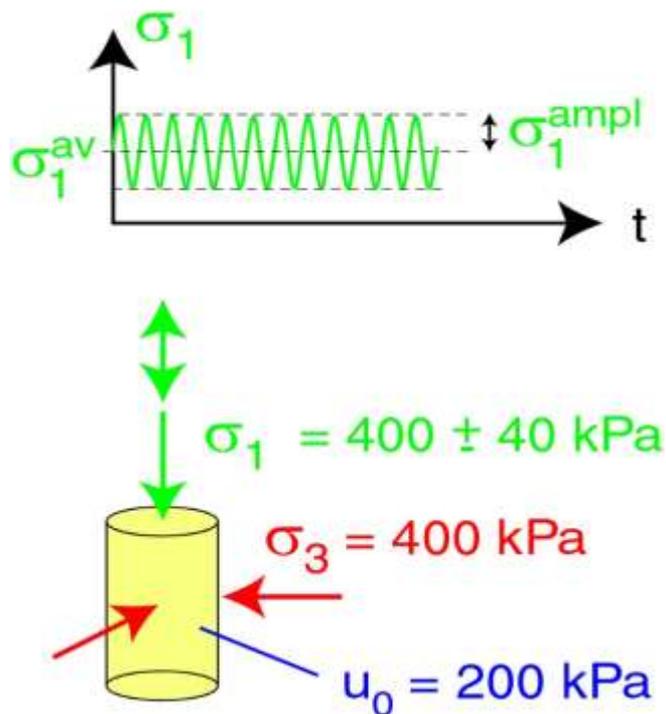
Material failure: Liquefaction due to cyclic loading (Deterioration of the grain skeleton structure)

Resistance of the grain skeleton against deterioration due to cyclic or dynamic loading depends upon:

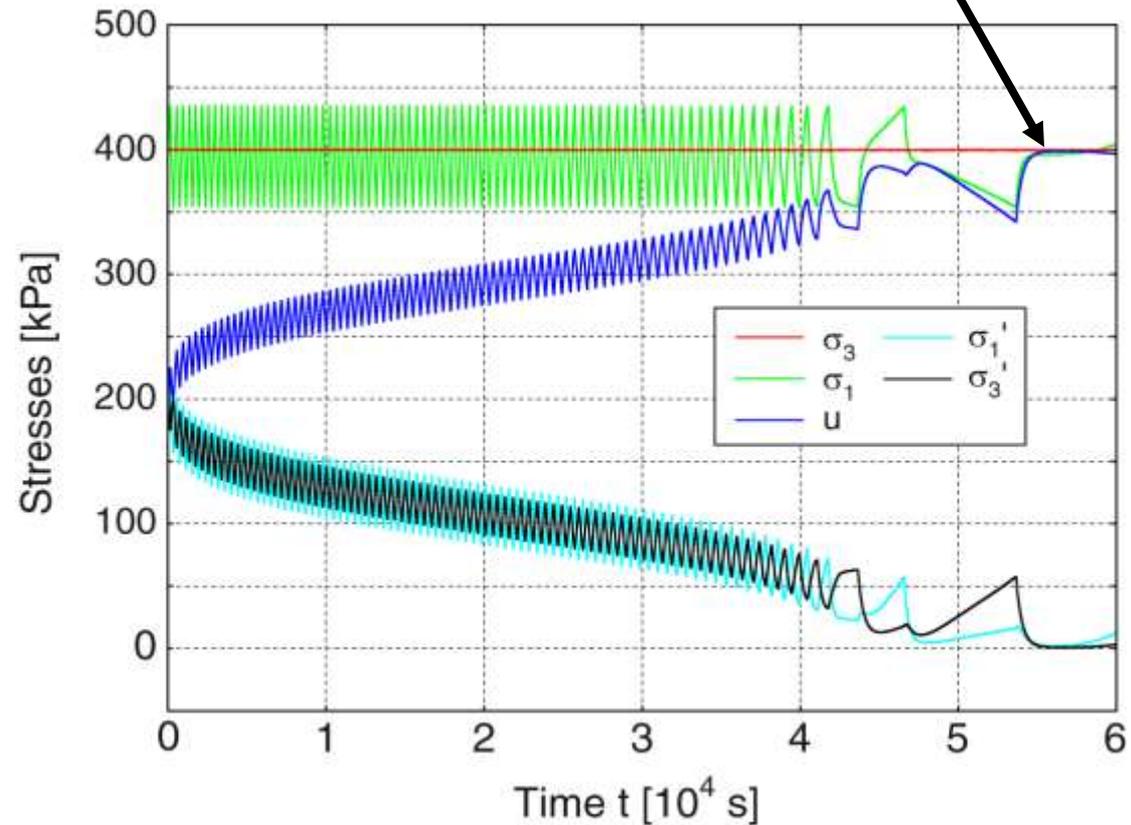
- Grain size distribution (including fines content) and grain morphology
 - Relative density
 - Deposition method (artificial slopes) or genesis (natural slopes)
 - Preloading (static or dynamic) due to pre-seismic activity
 - Empirical relations between CPT or SPT resistance (pressure dependent) or correlations of the pressure dependent shear velocity versus the resistance CRR as indicator for possible liquefaction (laboratory tests on undisturbed samples)
- CRR = f (Density, N:number of cycles, fabric)**
- **Material laws have to account for: limit and attractor states, historiotropy**

Undrained material behaviour

IBF-tests on a fine sand $I_D \approx 0.65$):



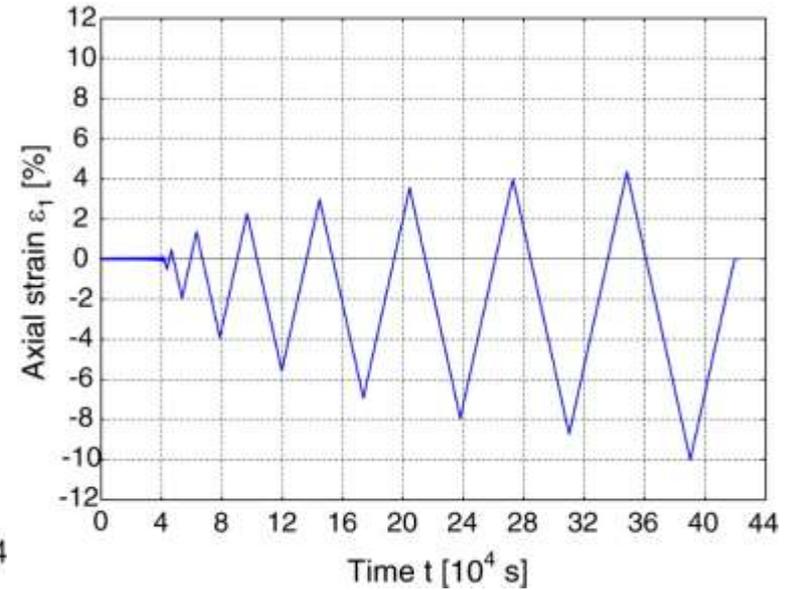
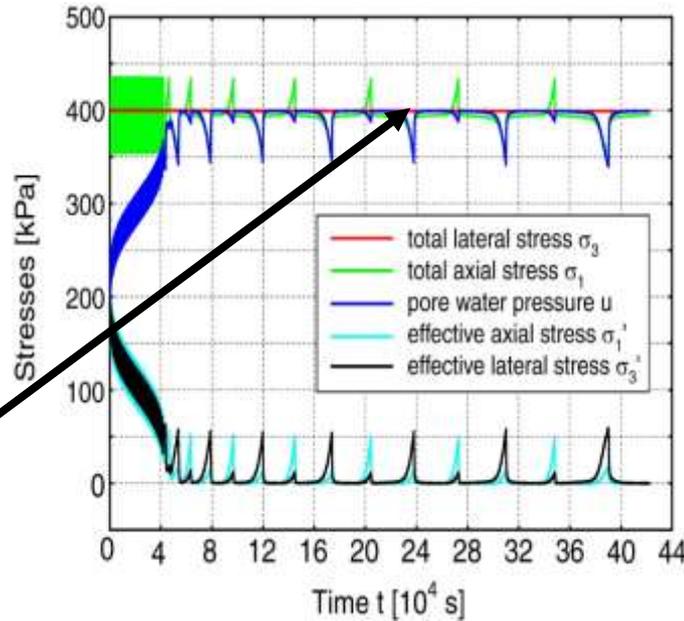
“initial liquefaction”



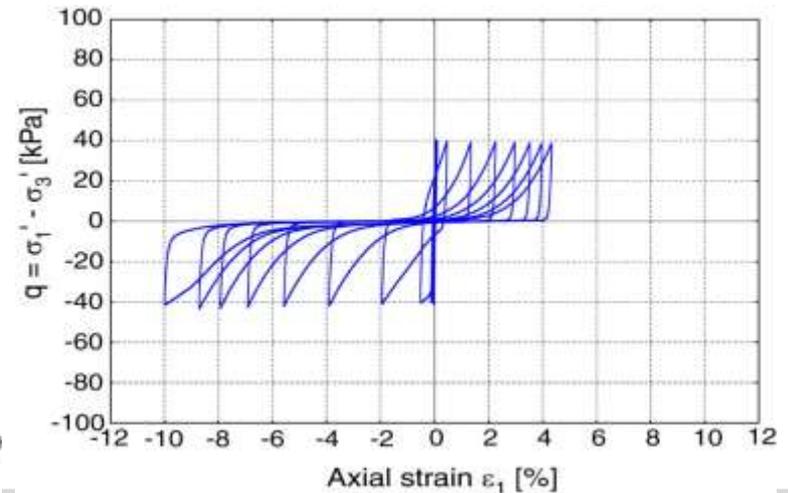
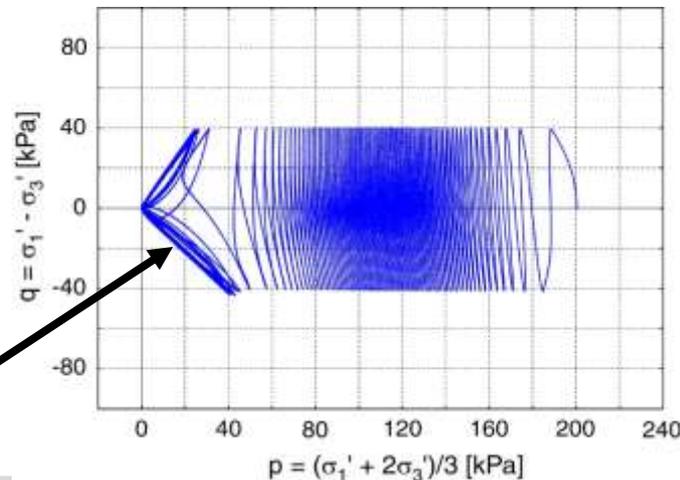
Undrained material behaviour

IBF tests on a fine sand :

“partial liquefaction“

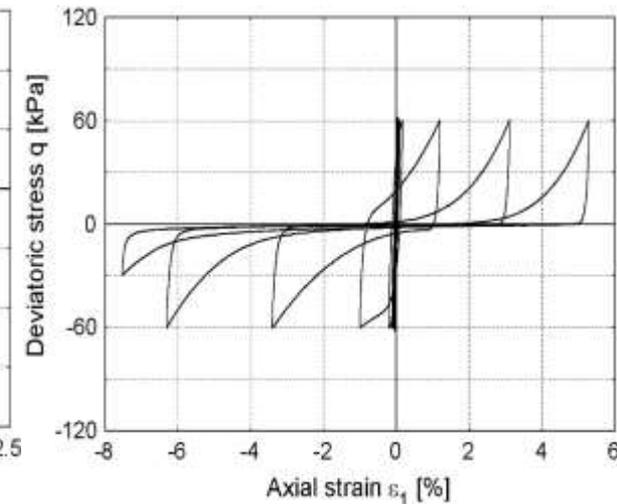
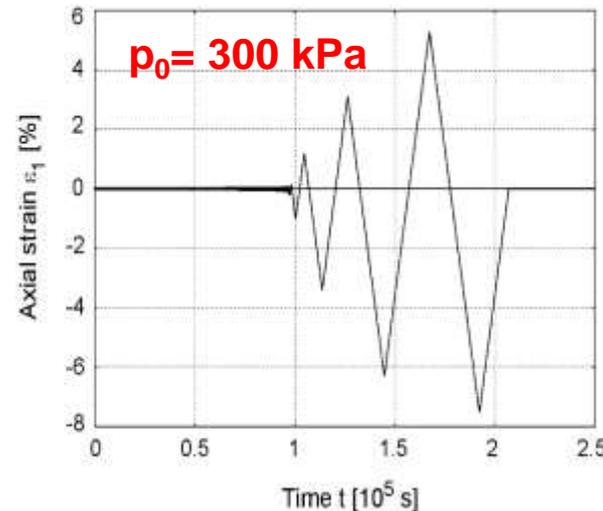
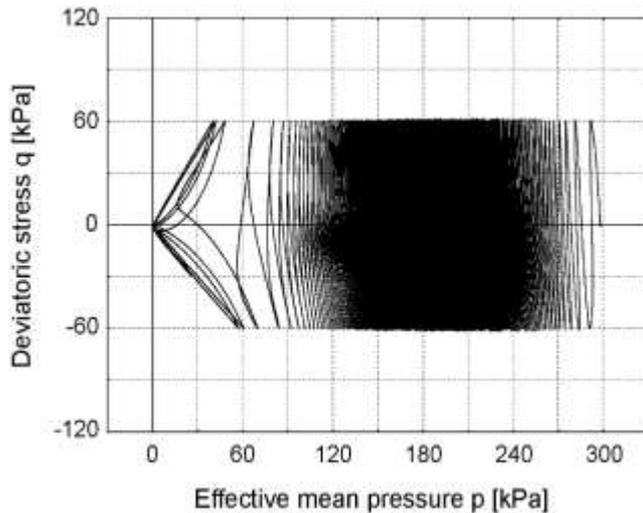
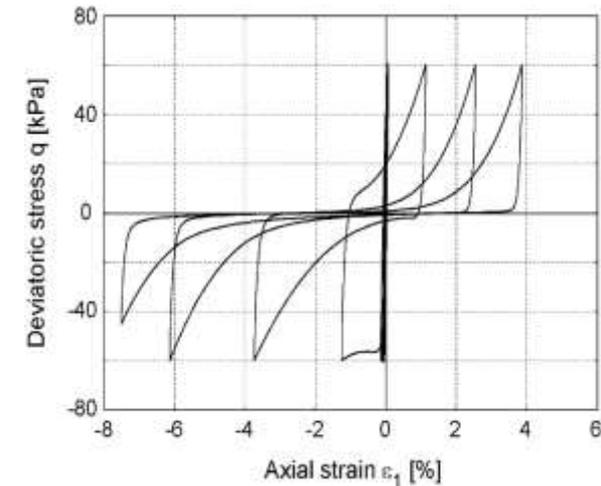
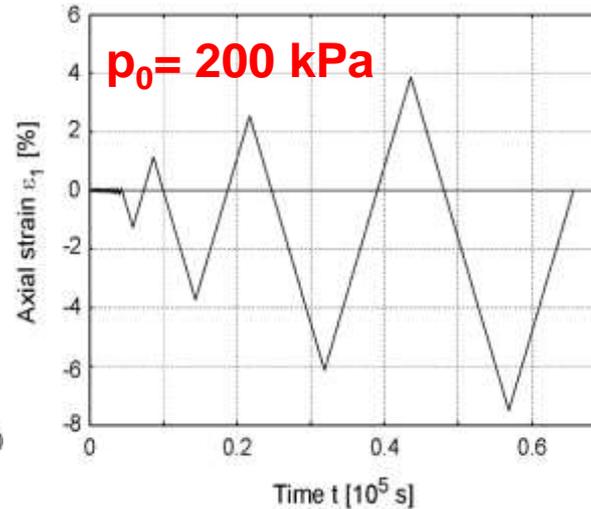
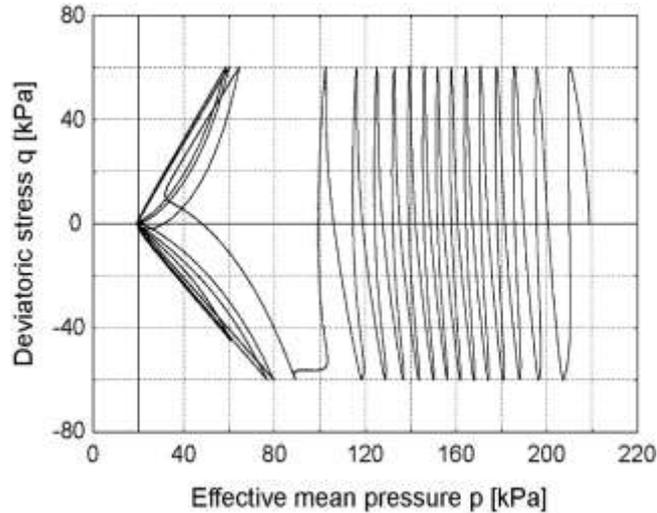


„cyclic mobility“



Undrained cyclic shearing - Attractors

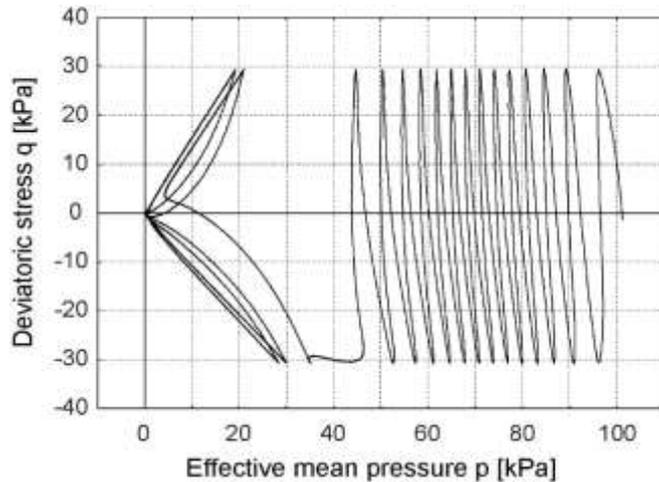
Medium dense fine sand $I_{d0} = 0,59 - 0,55$, $q^{ampl} = 60$ kPa, at different pressures p_0



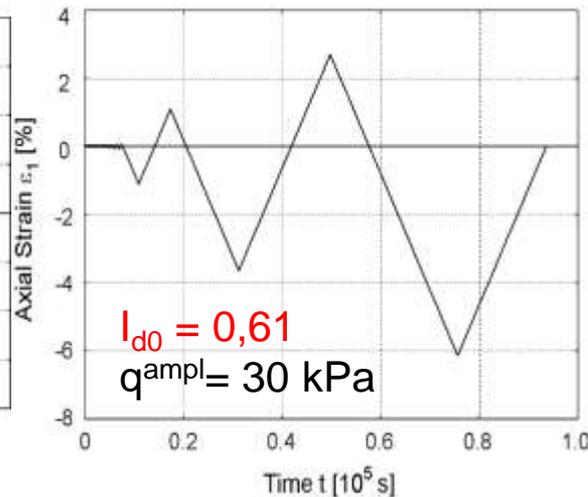
Undrained cyclic shearing - Attractors

Tests on the same initial pressure ($p_0 = 100$, $q^{\text{ampl}} = 25/30$ kPa, but with different densities)

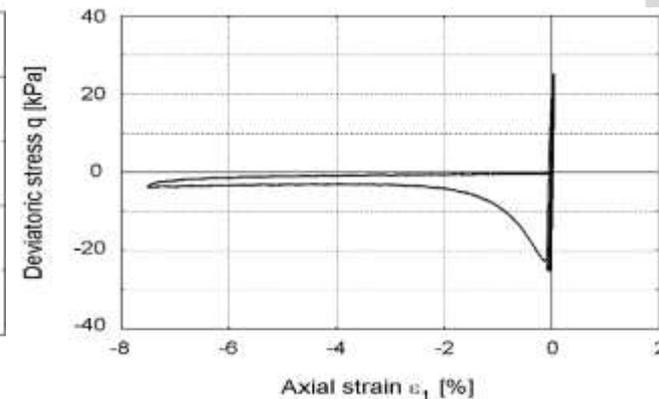
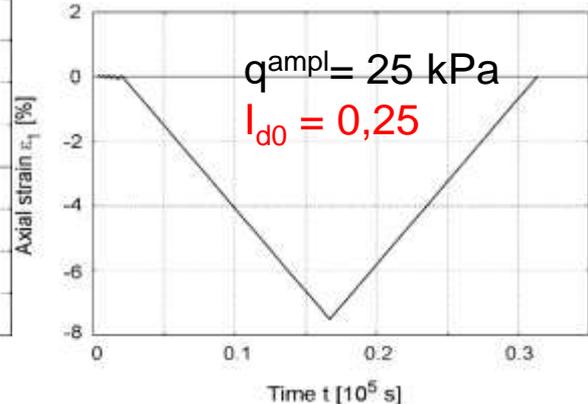
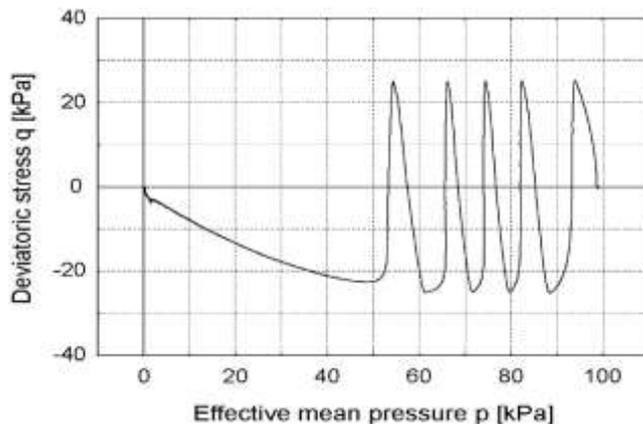
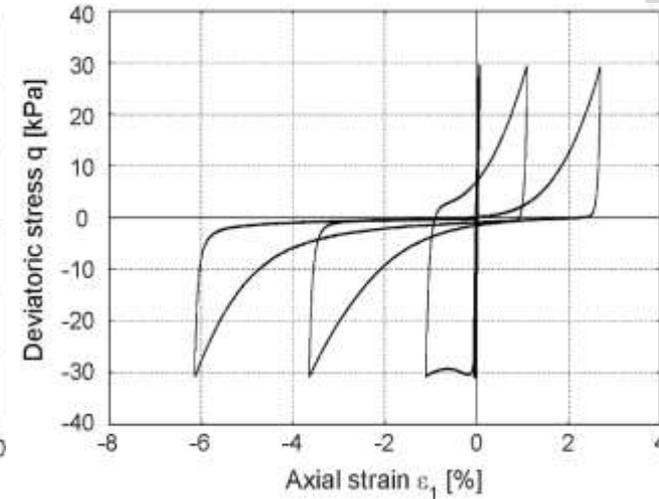
Effective stress path



Axial strain



Deviator stress versus axial strain

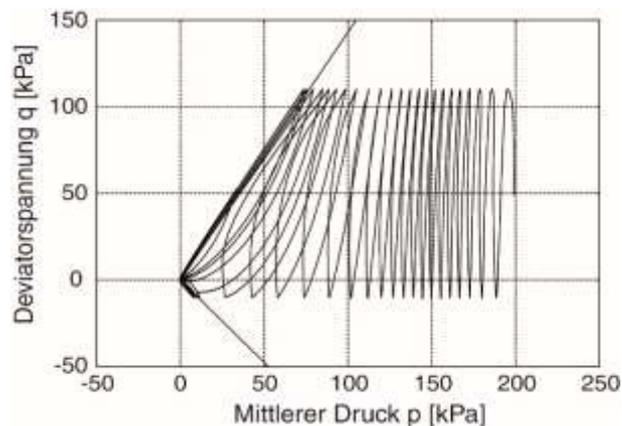


Undrained cyclic shearing with anisotropic shear stress - Attractors

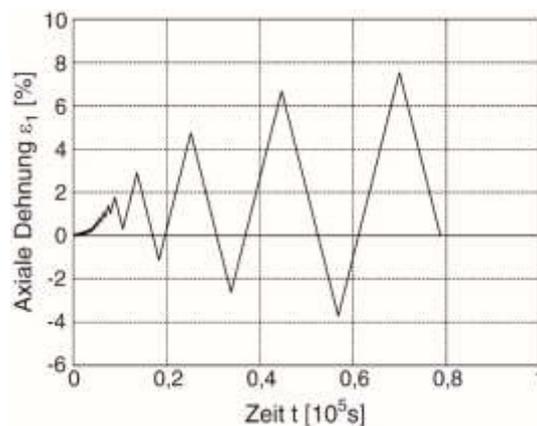
Tests with anisotropic initial stresses

($q_{\min} < 0$, $I_{d0} = 0,53$, $q^{\text{ampl}} = 60$ kPa):

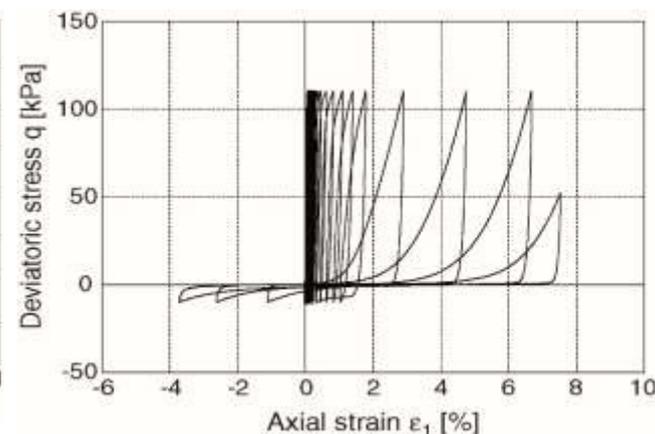
Effective stress path



Axial strain



Deviator stress versus axial strain

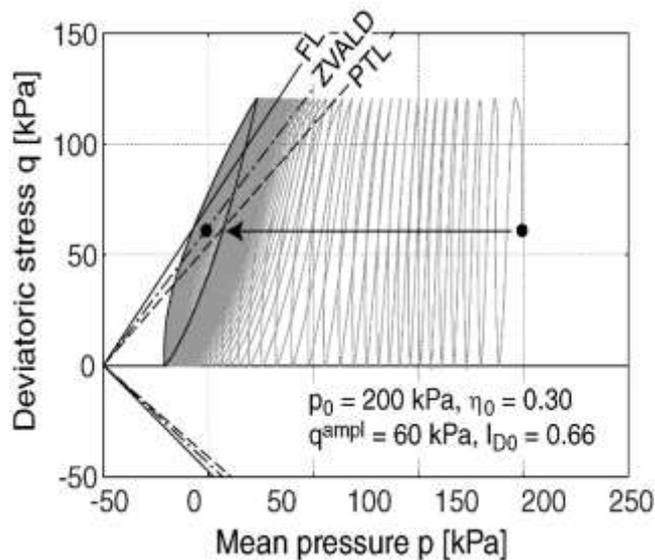


Cyclic mobility attractor for anisotropic initial stress lead to an asymmetric butterfly attractor (for $q_{\min} < 0$, $p = 0$ is often reached !!!!)

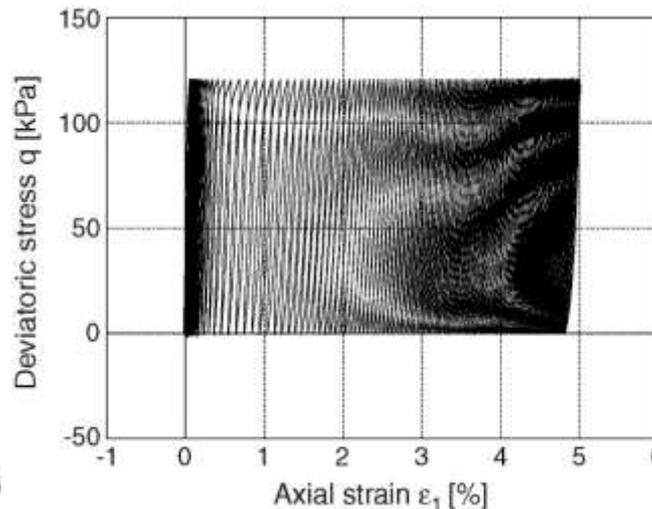
Undrained cyclic shearing with anisotropic shear stress - Attractors

Tests with anisotropic initial stress state and pulsating stress ($q_{min}=0$):

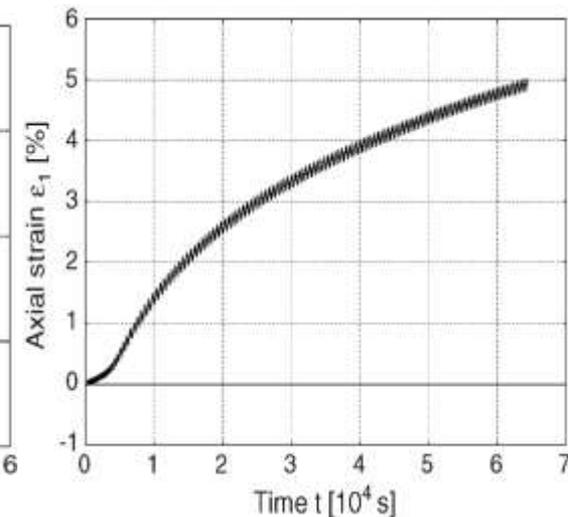
Effectiv stress path



Deviator stress versus axial strain



Axial strain



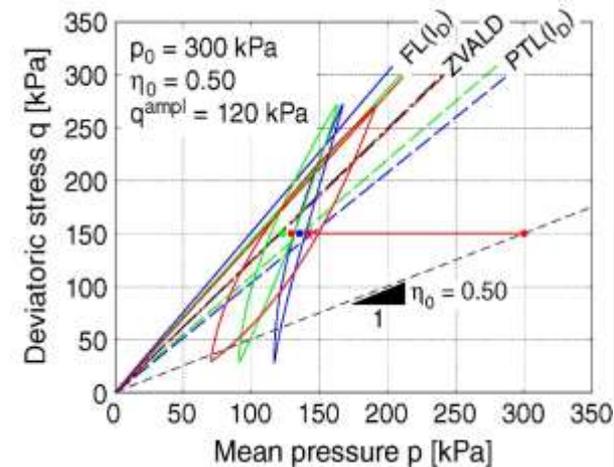
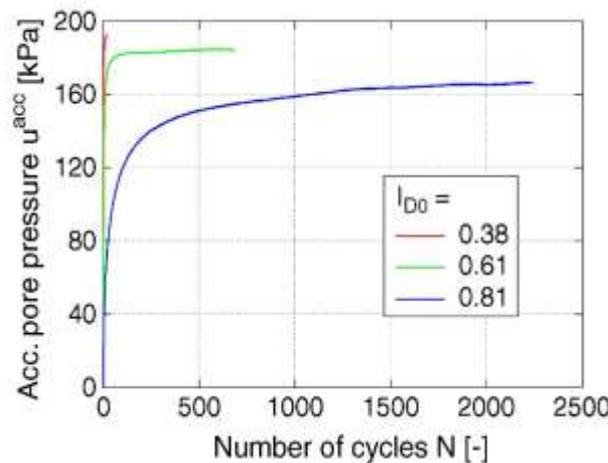
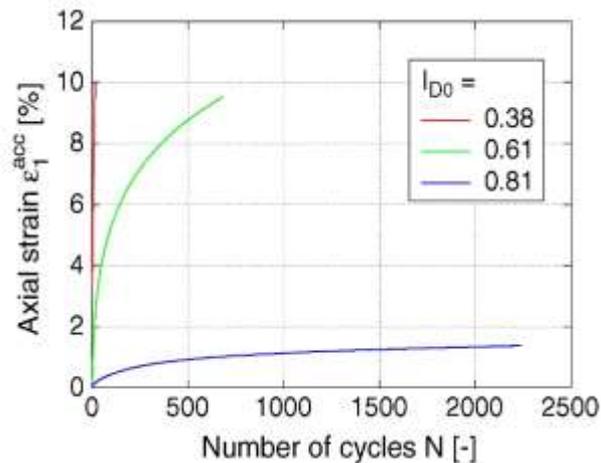
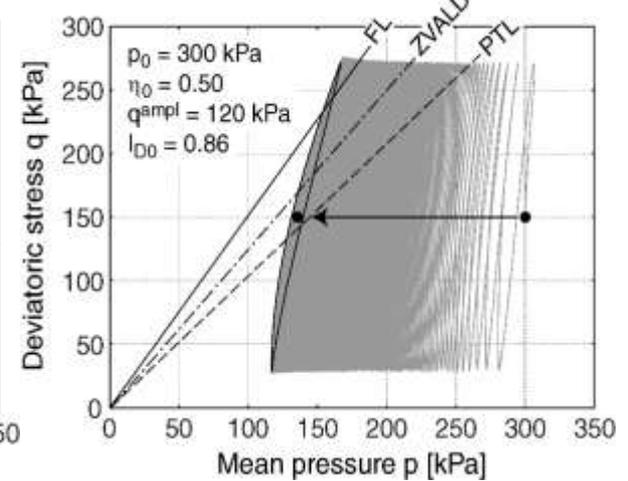
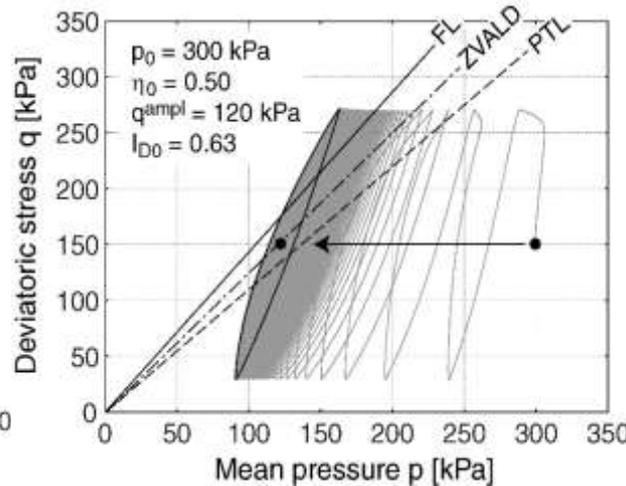
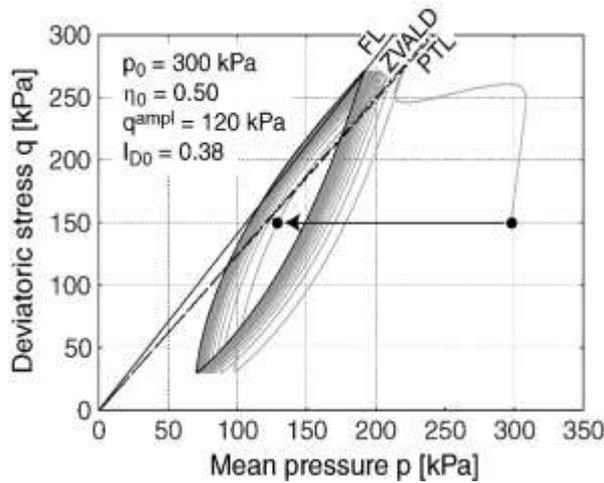
Limit cycle has the form of a lense not of a butterfly!!

With increasing number of cycles N the accumulation rate became smaller!!

$p=0$ is never reached but a limit stress $p \neq 0$!!

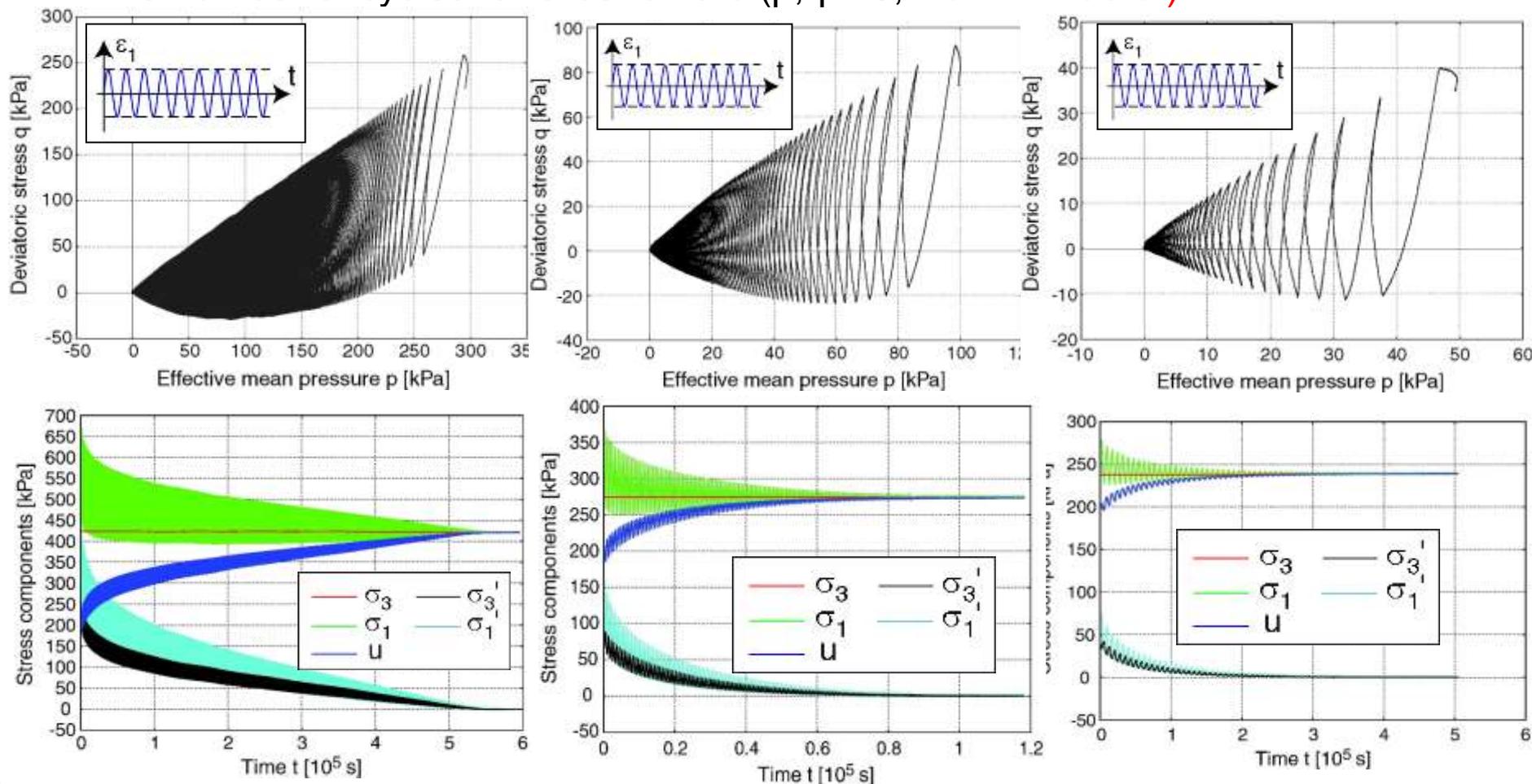
Undrained cyclic shearing with anisotropic shear stress - Attractors

Influence of the density under the same initial stress regime ($q_{min} > 0$), and the same cyclic stress amplitude (lose: $I_{D0} = 0,38$, medium dense $I_{D0} = 0,63$ and dense: $I_{D0} = 0,86$)

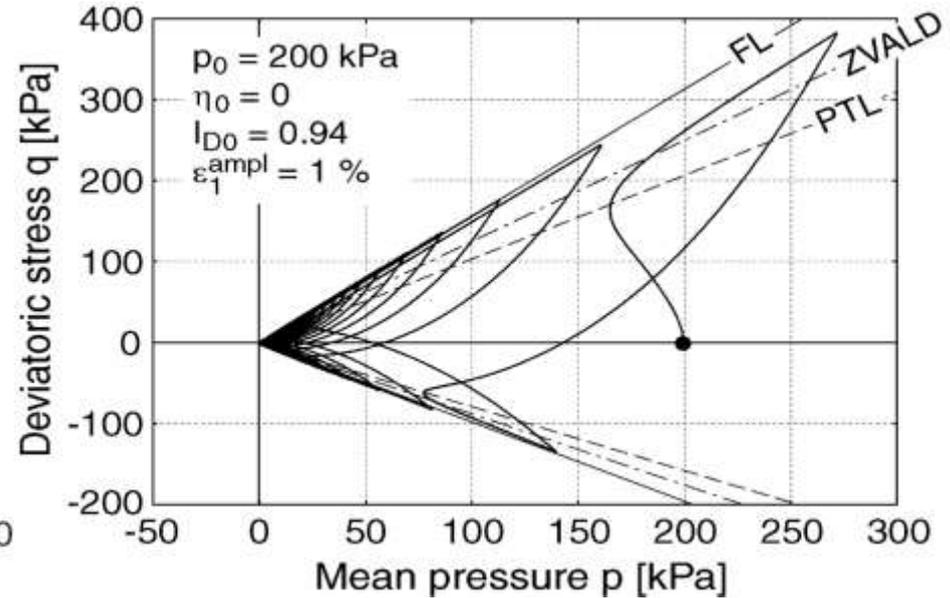
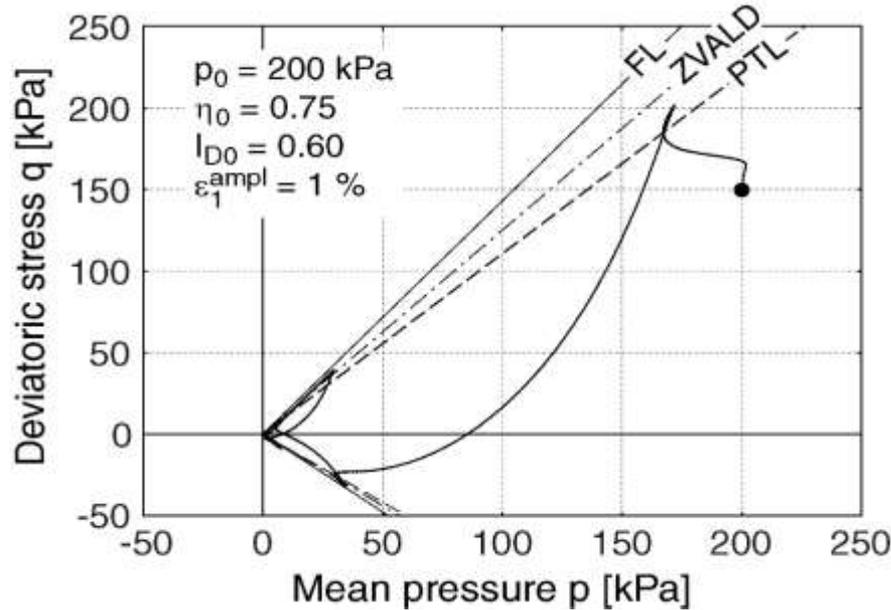


Undrained shearing with strain control - Attractors

Effective stress paths for the same initial stress ratio $\eta=0,75$, density and strain amplitude $\varepsilon_1 = 6 \cdot 10^{-4}$ but different **isotropic stress**. Relaxation of the effective stress with the number of cycles towards to zero ($p, q = 0$, **Point-Attractor**)



Strain control with larger amplitudes

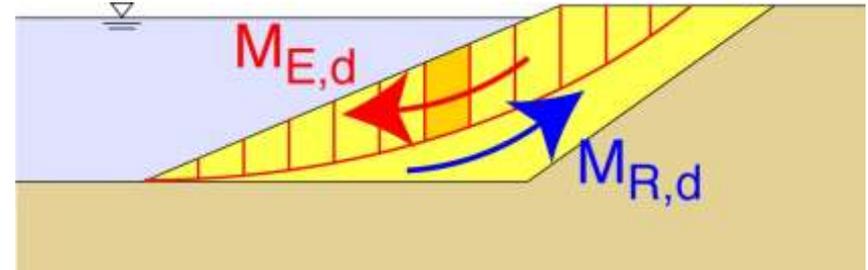


- **Large cyclic strain amplitudes** (in the order of 10^{-2} lead always to the butterfly effect for medium and dense sands **independent from the initial values of e und σ** .
- At large strain amplitudes after a initial contractant behaviour the dilatancy takes over and forces the stress path to cross the phase-transformation line (PTL) and the material creates more space for the following contractancy after the strain reversal. This additional space is used from the material to cross the PTL-line on the extensional regime and to follow the failure with dilatant behaviour. After the strain reversal the material reaches the butterfly attractor (not the **Point attractor**)

Dynamic stability analysis and requirements on constitutive equations

Constitutive laws have to describe:

- All the **attractor states** cyclic mobility, lens and point attractors
- Steady state behaviour
- Dilatancy and contractancy effects
- Hysteresis effects



Only under principal satisfaction of the above criteria and satisfactory calibration of the material parameters a performance based design is possible.

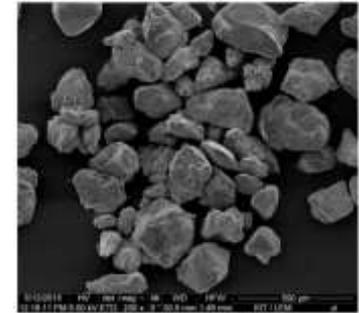
The slope after an initial movement due to a seismic event may slide in order to find a new equilibrium state.

The amount of the permanent deformation may be checked against the serviceability of the utilities or the nearby structures (displacement or performance based design).

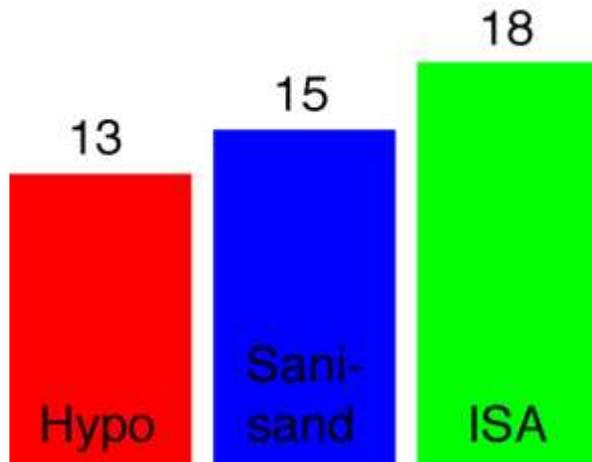
Modelling the cyclic behaviour

Only a few families of constitutive laws are suitable for the description of the cyclic material behaviour

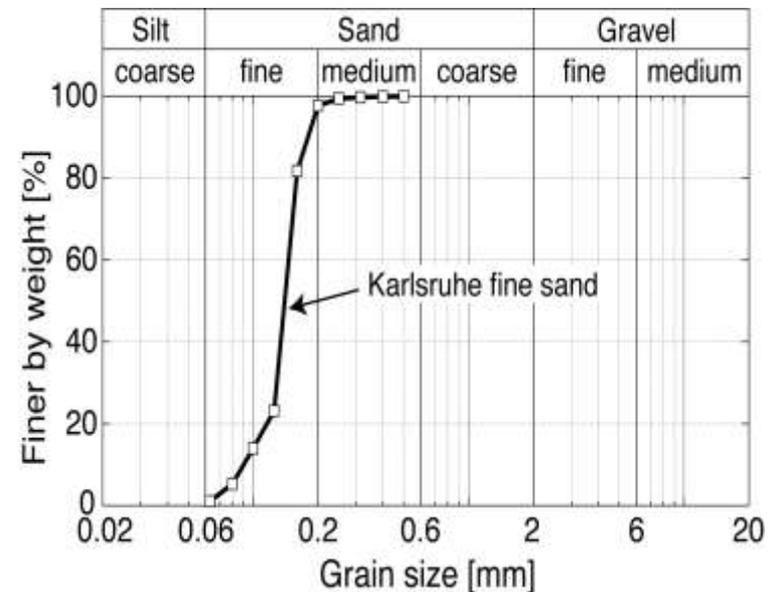
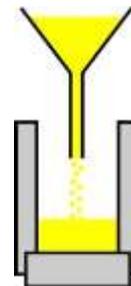
- **Hypoplasticity with intergranular strain** (von Wolffersdorff, 1996, Niemunis & Herle, 1997)
- **Sanisand** (elasto-plastic model, Dafalias & Manzari, 2004)
- **ISA-Model** („Intergranular Strain Anisotropy“, Fuentes and Triantafyllidis, 2015)



Number of material parameters to be determined:

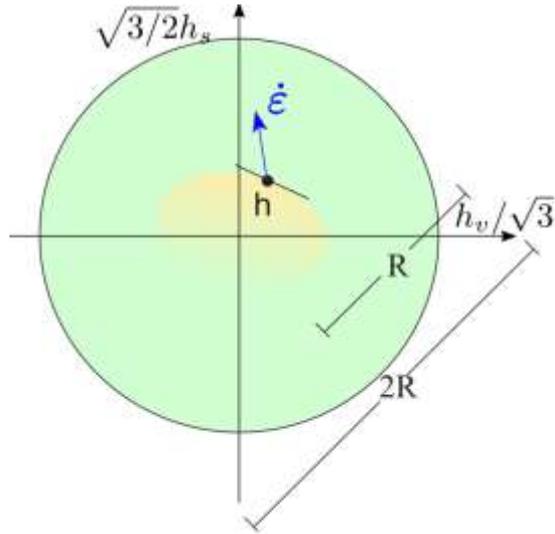


• **Material tested:**
 (Karlsruhe fine sand) $d_{50} = 0,14$ mm, $C_u = 1,5$



Schematic view of the material models

Hypoplasticity with intergranular strain
(Niemunis and Herle, 1997)

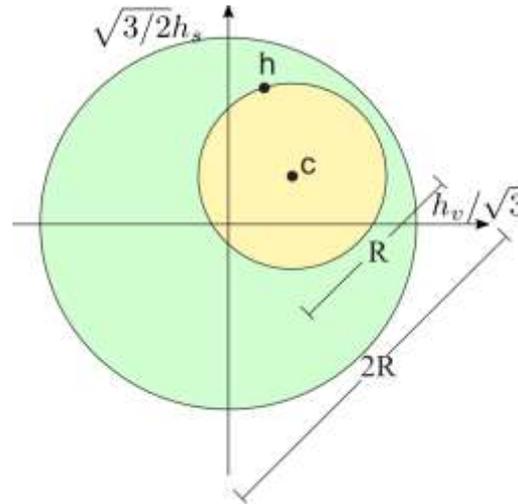


$$\dot{\sigma} = E : (\dot{\epsilon} - Y \mathbf{m} \|\dot{\epsilon}\|)$$

- Unloading: $\dot{\mathbf{h}} = \dot{\epsilon}$
- Loading:

$$\dot{\mathbf{h}} = \left(I - \frac{\vec{\mathbf{h}} \vec{\mathbf{h}}}{\rho^{\beta_r}} \right) : \dot{\epsilon}$$

ISA
(Fuentes and Triantafyllidis, 2015)

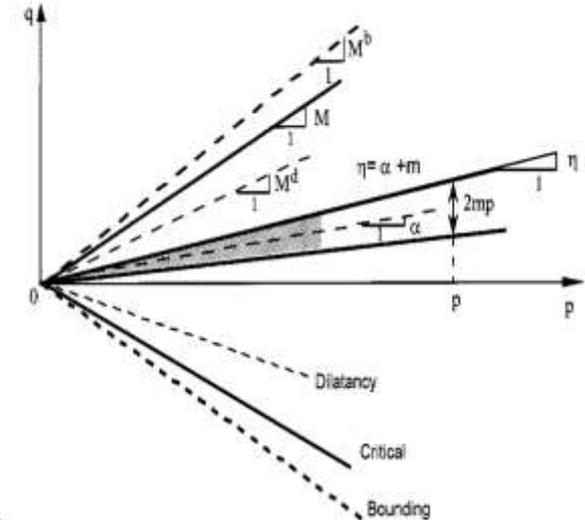


$$\dot{\sigma} = E : (\dot{\epsilon} - Y \mathbf{m} \|\dot{\epsilon}^p\|)$$

- Unloading: $\dot{\mathbf{h}} = \dot{\epsilon}$
- Loading:

$$\dot{\mathbf{h}} = \dot{\epsilon} - \dot{\lambda}(\mathbf{h} - \mathbf{c}) \rightarrow$$

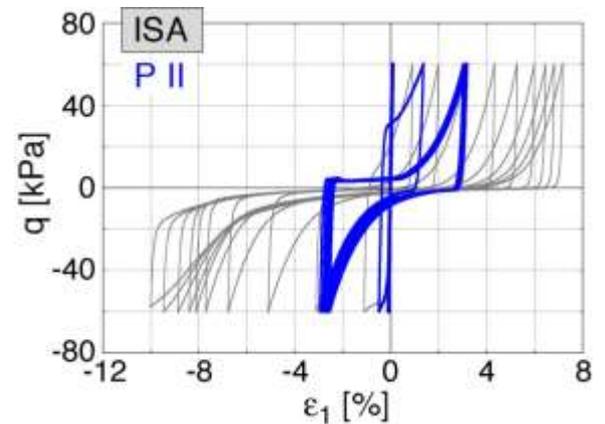
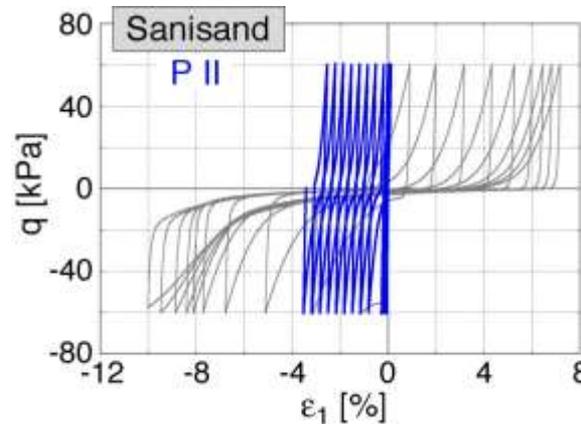
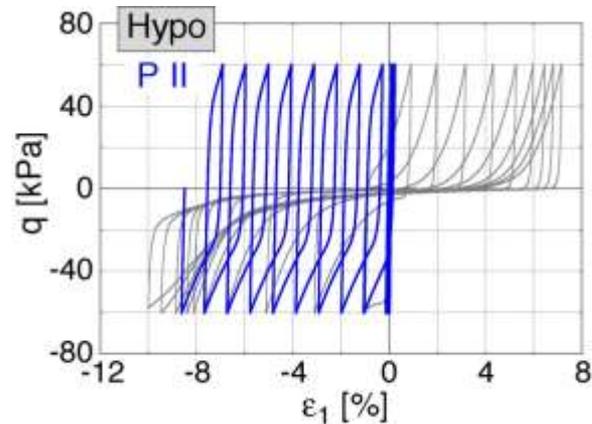
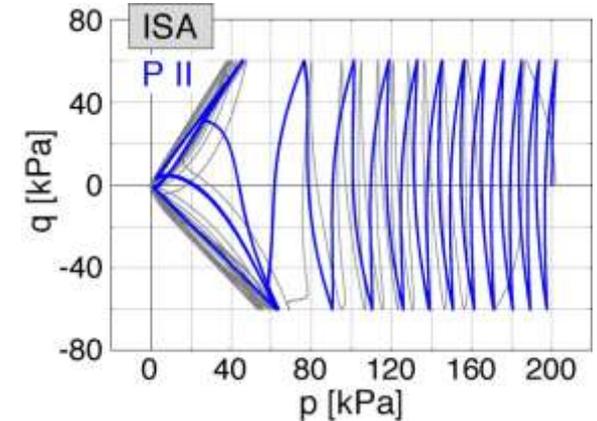
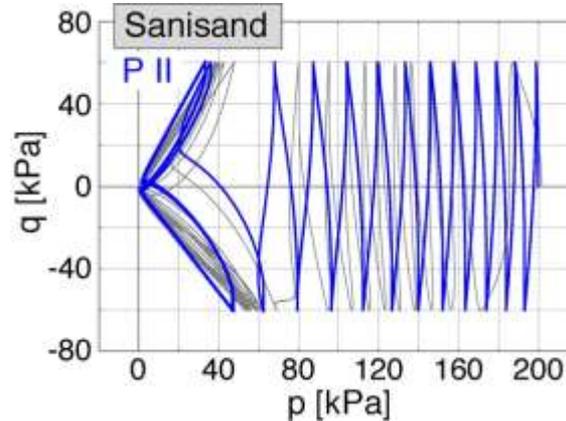
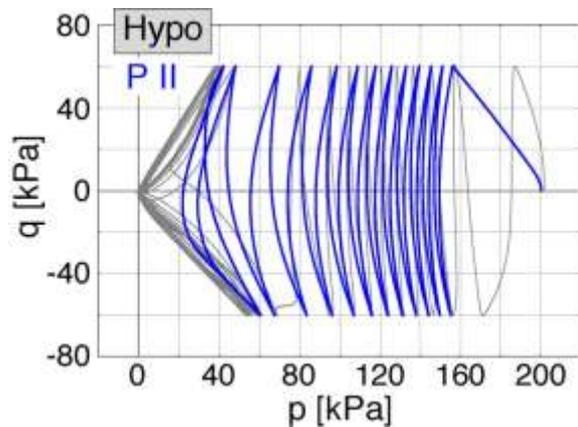
SANISAND
(Dafalias and Manzari, 2004)



Elasto-plastic model with dilatancy and bounding surfaces)

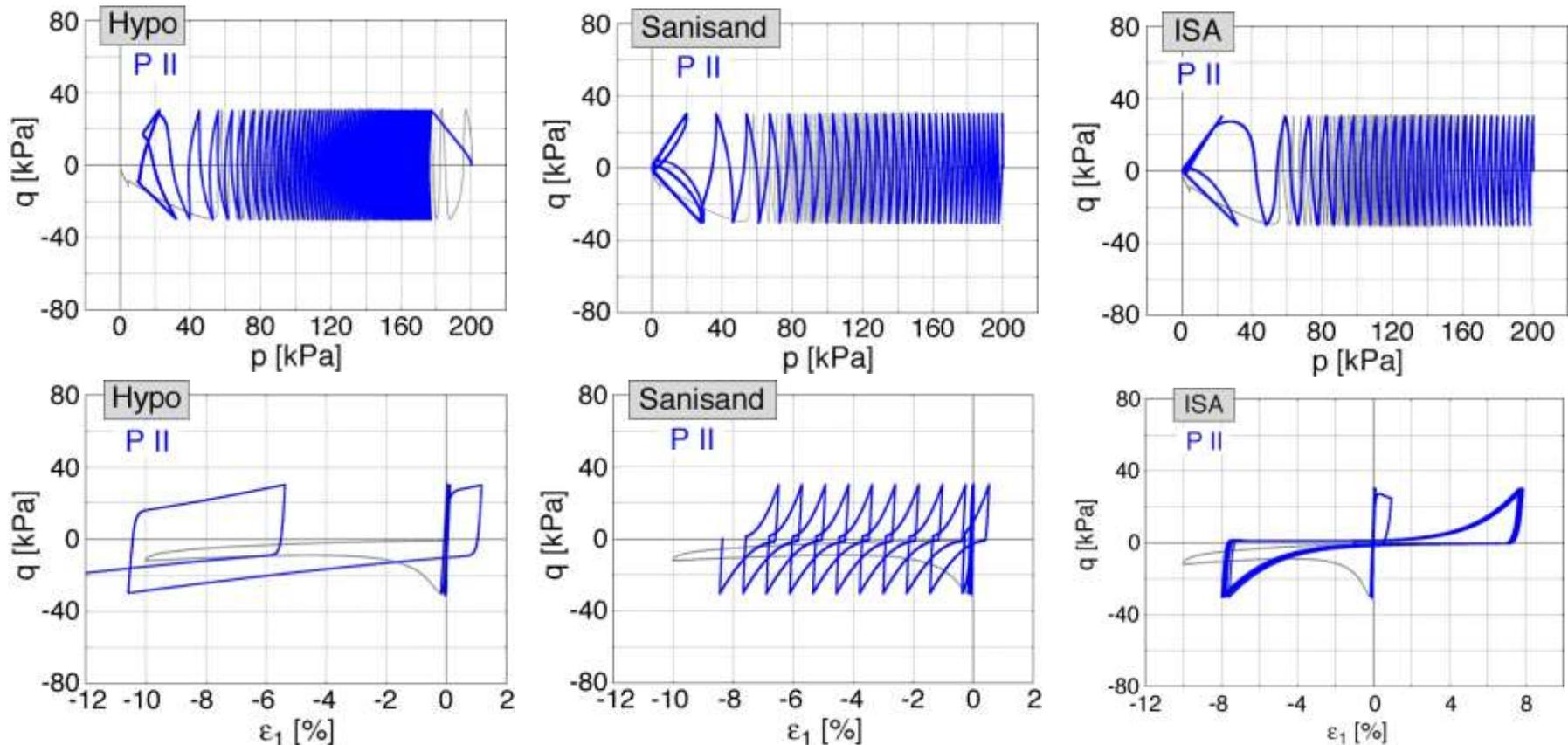
Simulations of triaxial testing

Undrained conditions with **isotropic initial mean stress**,
stress cycles, **medium dense** sand ($I_{D0} = 0,67$)



Simulations of triaxial testing

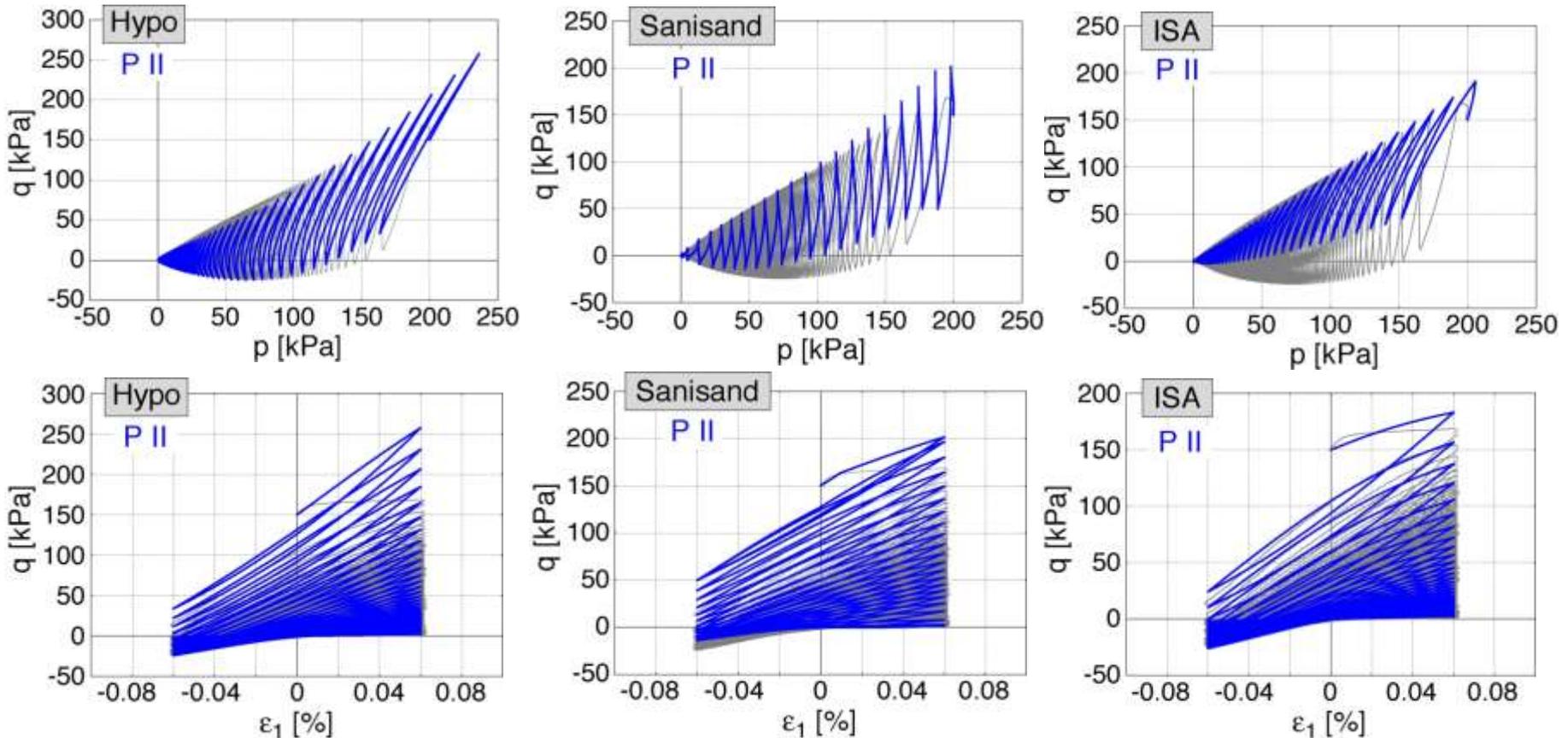
Undrained conditions, isotropic initial stress,
stress cycles, **loose density** ($I_{D0} = 0,27$)



→ Test: Failure within the first cycle on the extensional regime;
Model prognosis: either butterfly or eight-shaped effective stress path

Simulations of triaxial testing

Undrained conditions, **anisotropic initial stress**,
strain cycles with relatively small amplitudes $\varepsilon_1^{\text{ampl}} = 6 \cdot 10^{-4}$, **dense** ($I_{D0} = 0,64$)

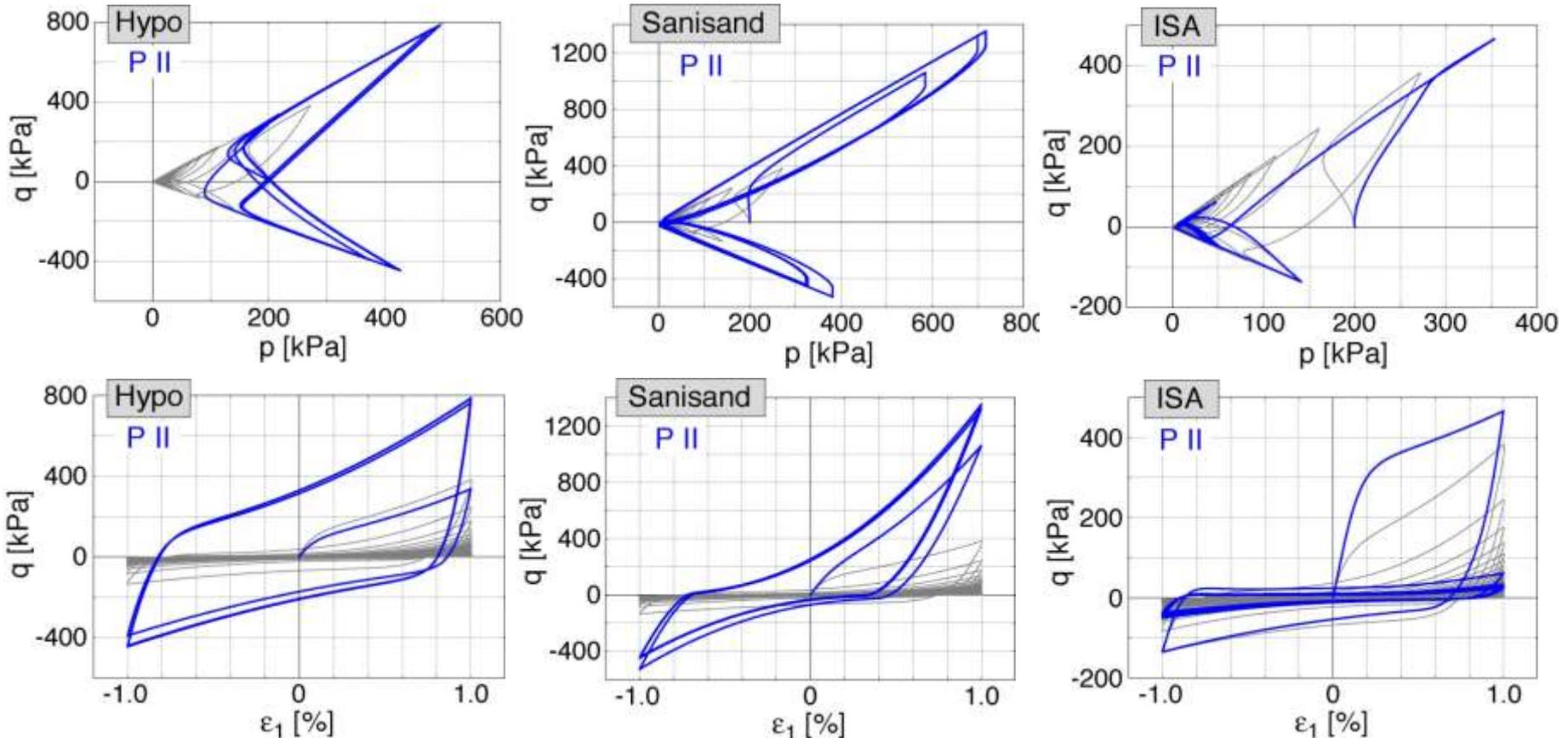


- qualitatively good reproducibility of the test results for all the models
- stress relaxation rate a bit too large for the sanisand model

Simulations of triaxial testing

Undrained conditions, isotropic initial stress,

strain cycles with relatively large amplitude $\varepsilon_1^{\text{ampl}} = 1 \cdot 10^{-2}$, dense ($I_{D0} = 0,94$)

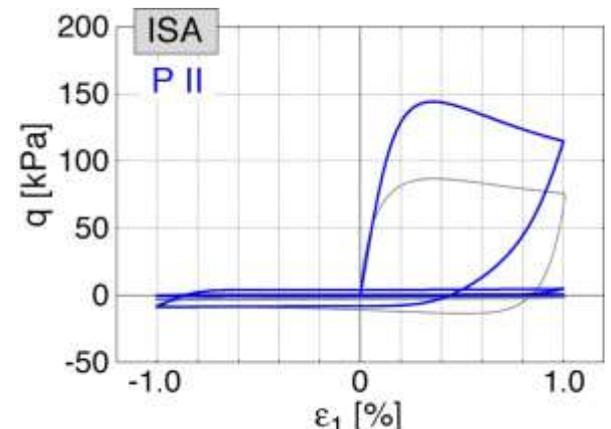
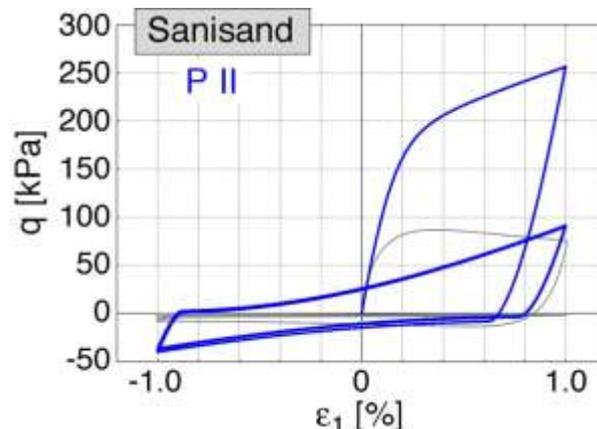
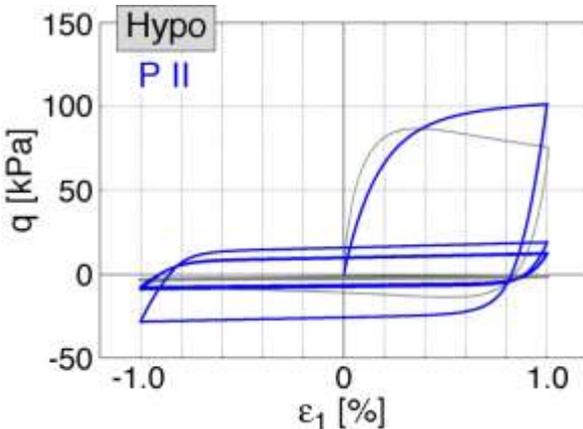
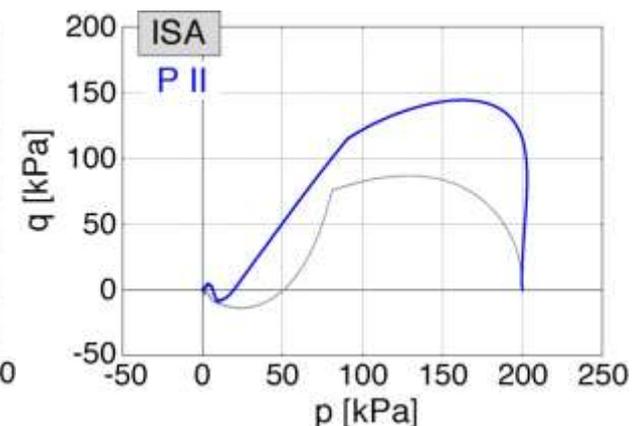
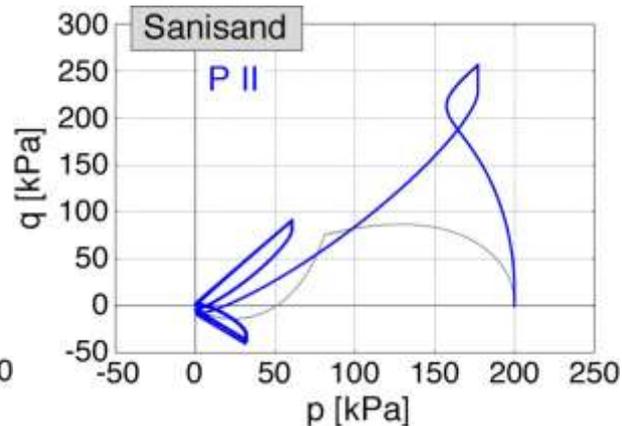
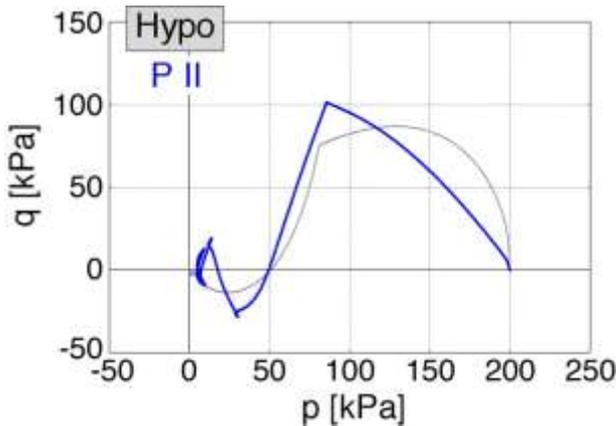


→ Test ended at $p = q = 0$, model prognosis either as an eight shaped stress (Hypo) or large (Sanisand) or small (ISA) „butterfly“ attractor

Simulations of triaxial testing

Undrained conditions, isotropic initial stress,

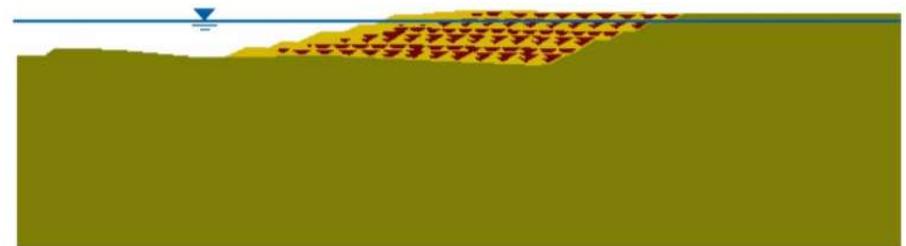
strain cycles with relatively large amplitude $\varepsilon_1^{\text{ampl}} = 1 \cdot 10^{-2}$, loose ($I_{D0} = 0,26$)



→ Test ended at $p = q = 0$, model prognosis as an eight shaped stress path (Hypo), „butterfly“ (Sanisand) or approx. in the stress point $p = q = 0$ (ISA)

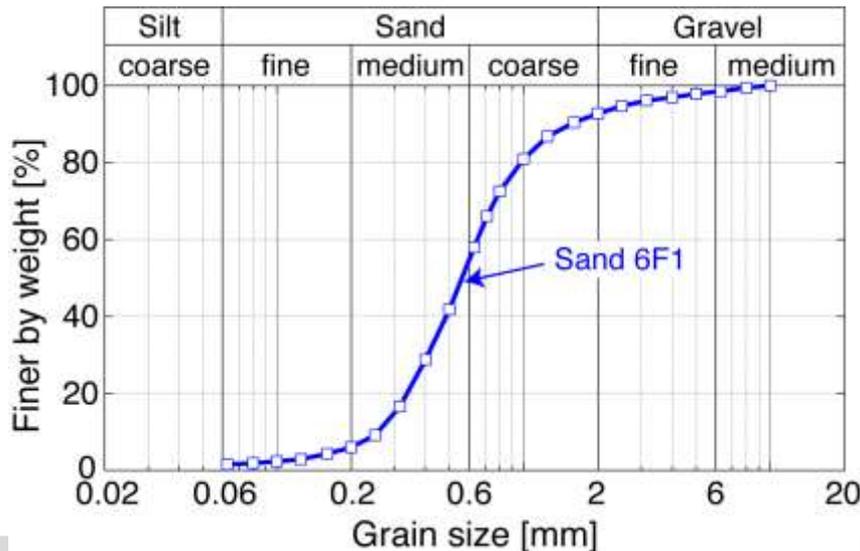
Example of a dynamic analysis on a slope in a residual lake after the lignite mining operations

- Creation of a **slope profile** consisting of cohesive and non cohesive materials
- Aprox. **undrained conditions** under the **water table** especially during seismic events (conservative assumption)

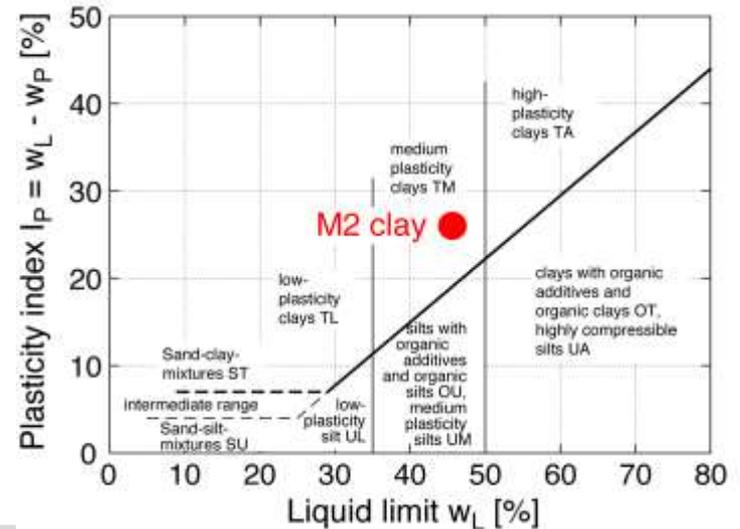


Materials (examples)

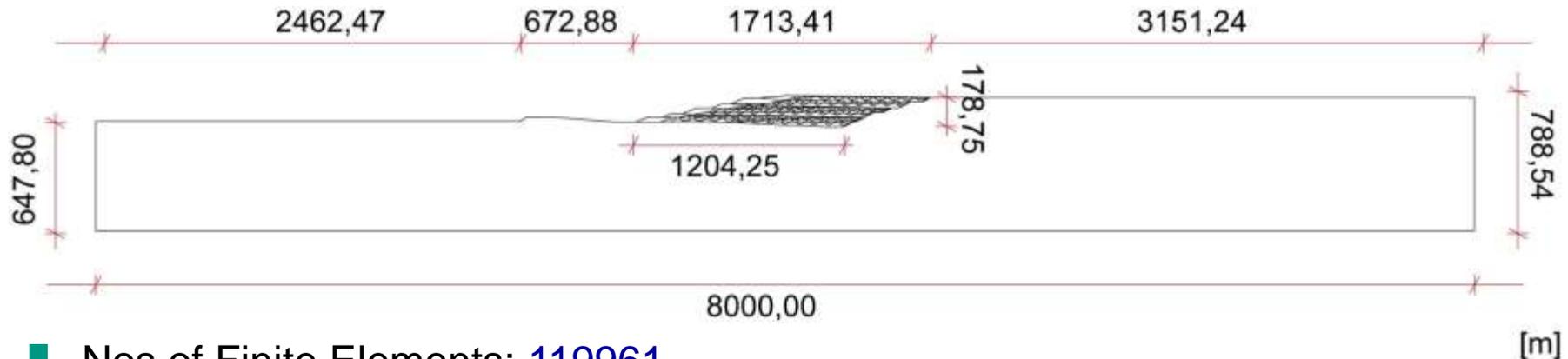
■ Sand



■ M2 -Clay



Slope simulation model

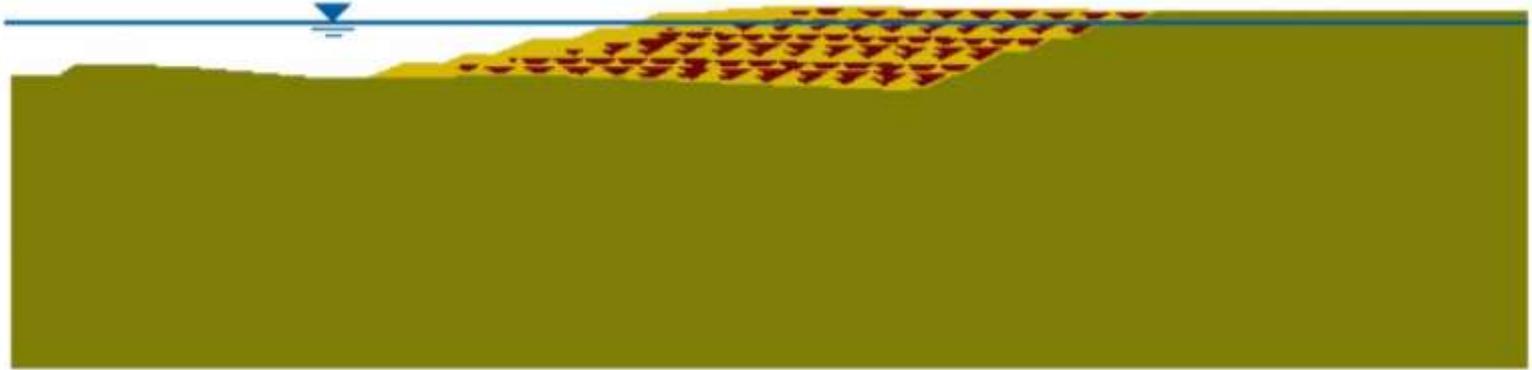


- Nos of Finite Elements: 119961
- Element type: CPE4R und CPE3 (ABAQUS)
- Element size: in the slope **2x2 m**, beneath the slope up to **7x7 m**, and close to the side boundaries up to **50x50 m**
- Stress dependent initial void ratio distribution in the slope ($I_{D0}=0,3$) and in the underlain undisturbed soil ($I_{D0}=0,7$)

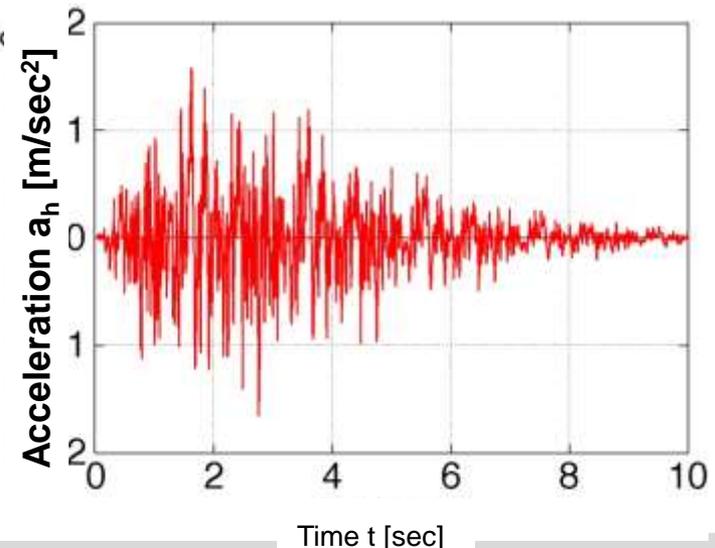
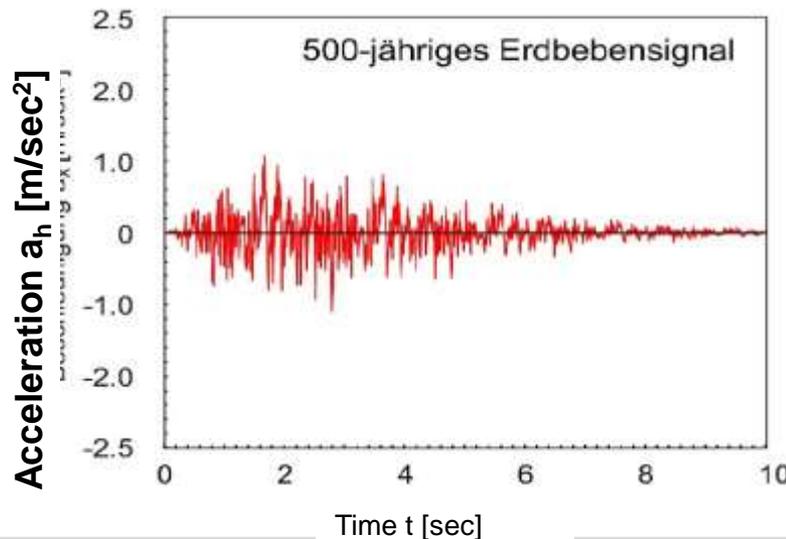


Deformation behaviour of one slope under seismic excitation: FE-Simulation results

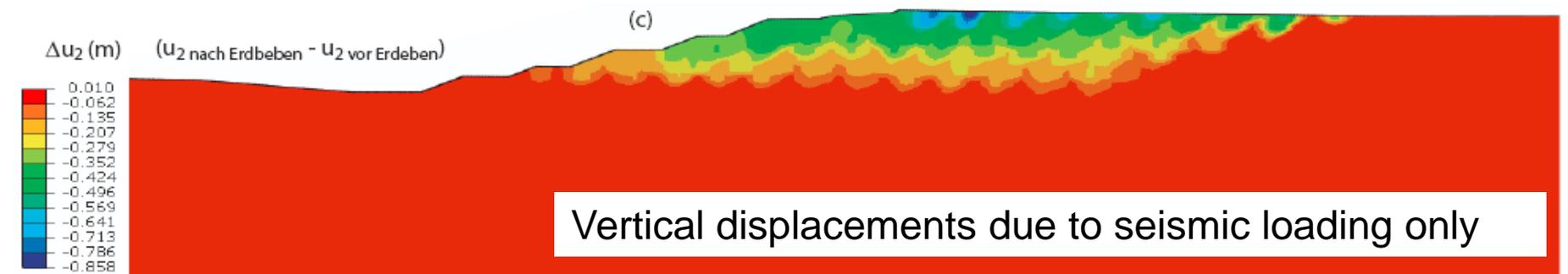
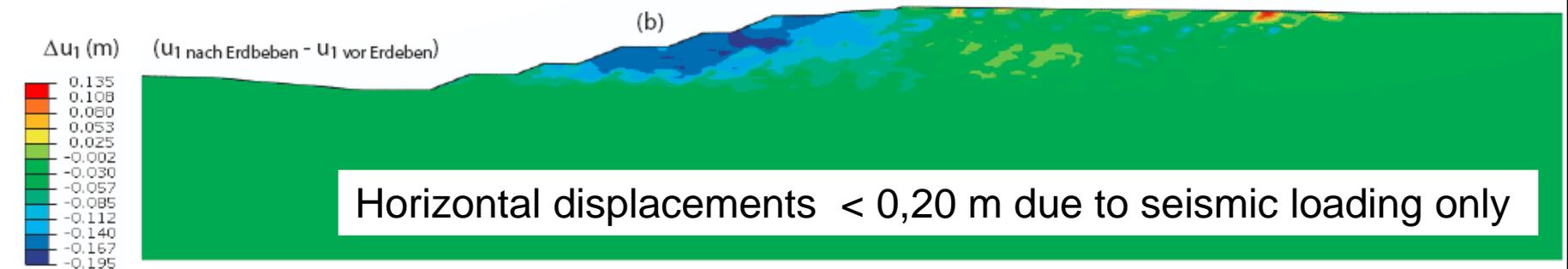
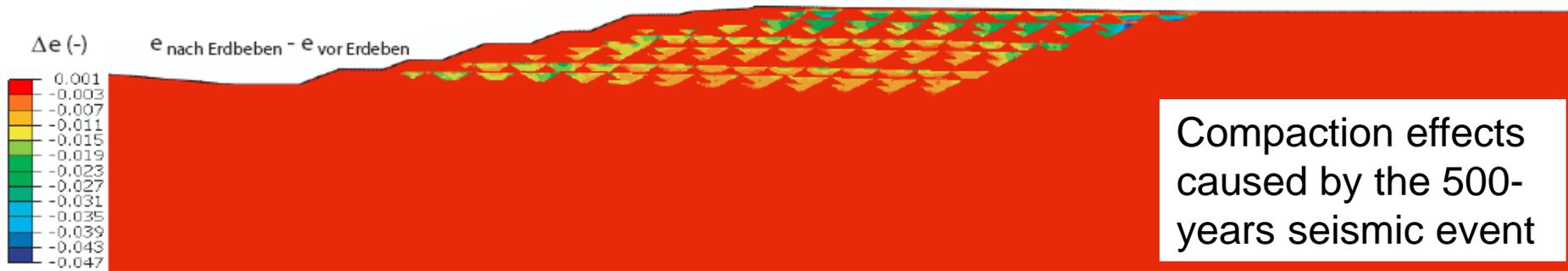
Model



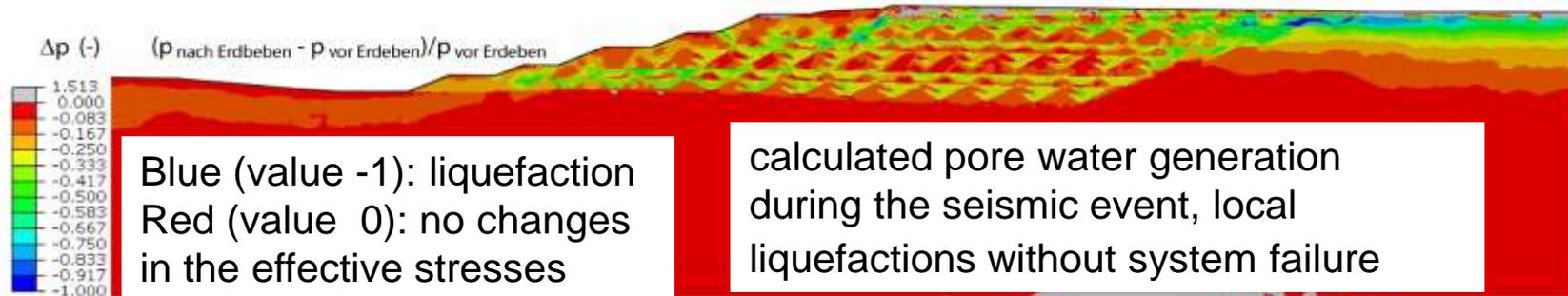
Synthesized seismic accerelogramms for the lower Rhine river basin based on the recurrence return period of 500-years (without water) and of 2500-years (WL 10 m below GL) with the magnitude M 6 on the basis of the FE – model (rock surface)



Deformations due to the 500-years seismic event



Deformations of a residual lake slope under a 2500-years excitation: Results of the FE-Simulations

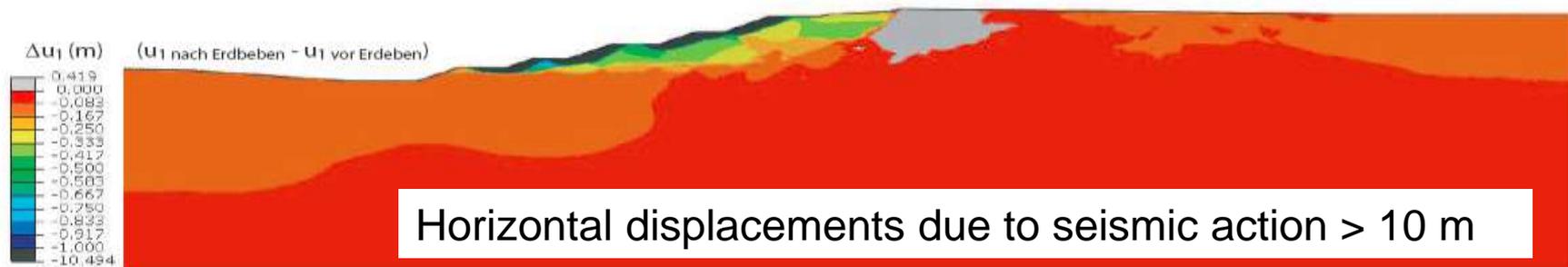
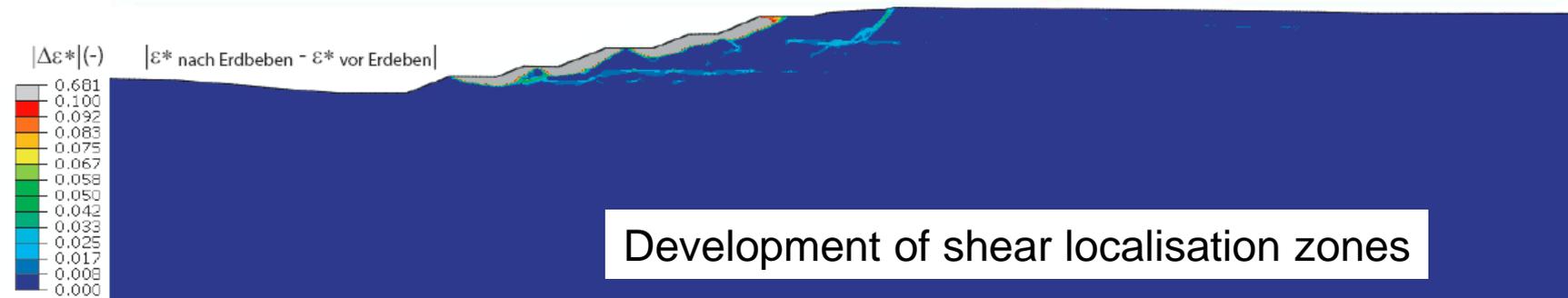
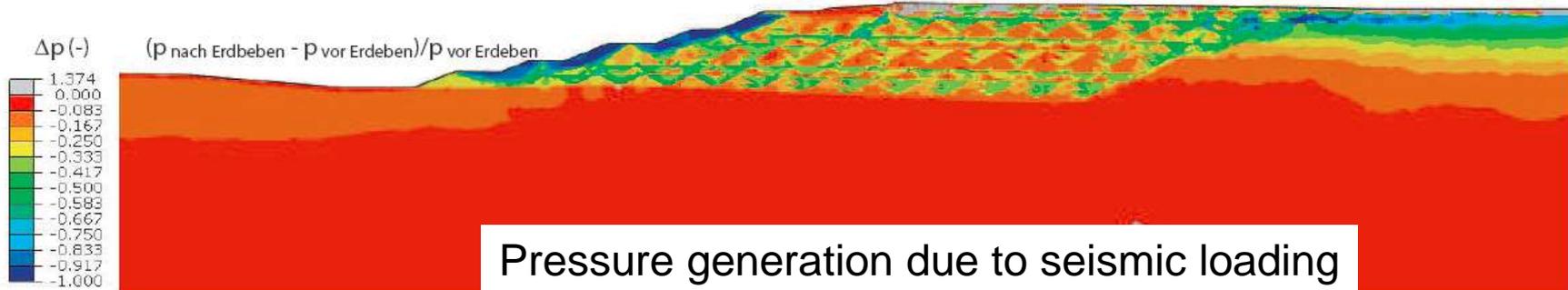


Maximum total displacements ca. 0,8 m



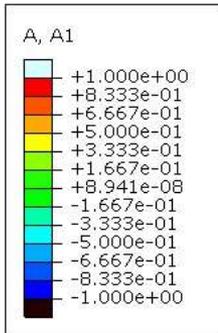
FE- Simulations for a seismic event of longer recurrence periods than 2500-years

Maximum acceleration on the underlain rock $2,1 \text{ m/s}^2$ (PGA ca. $0,5g$)

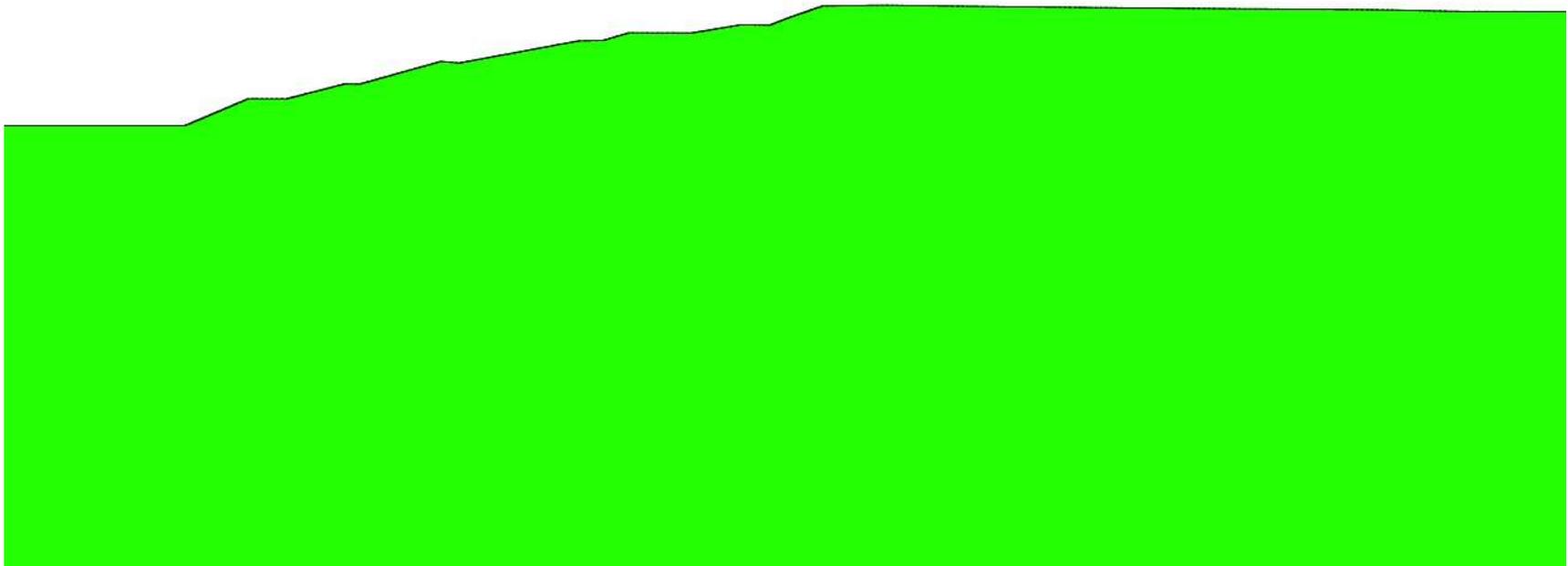


Deformations of a residual lake slope under a 2500-years recurrence seismic excitation: FE-Simulations

Slope consisting of sandy material only

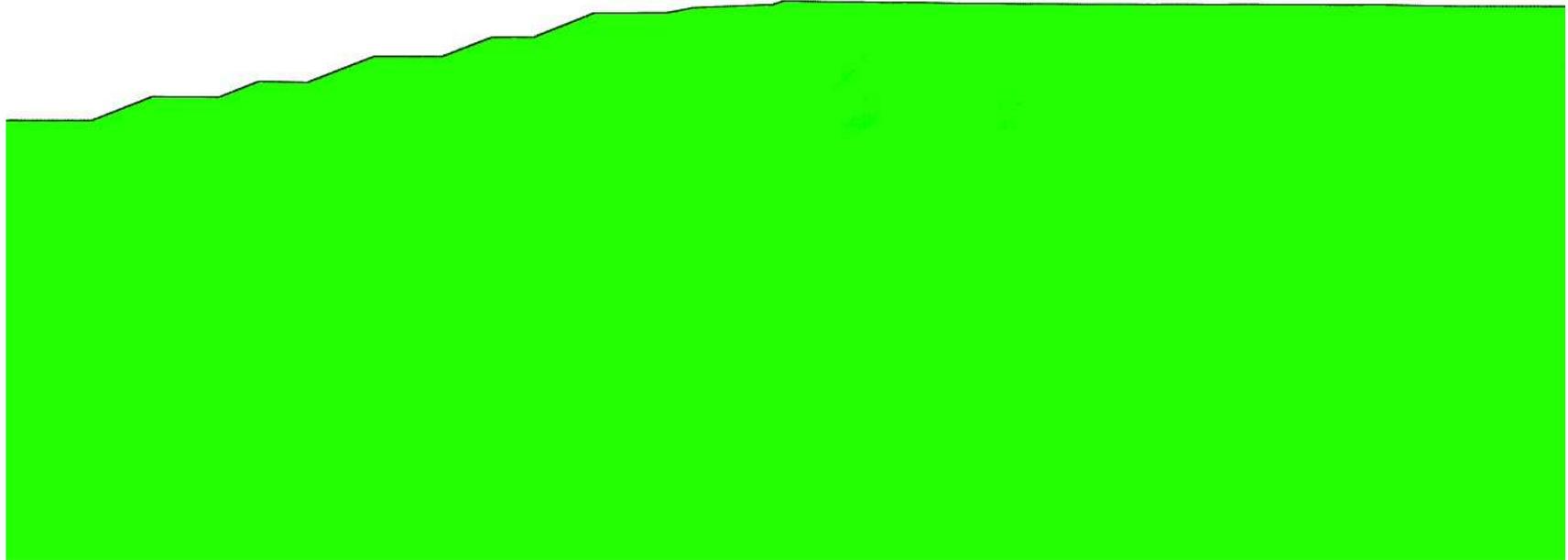
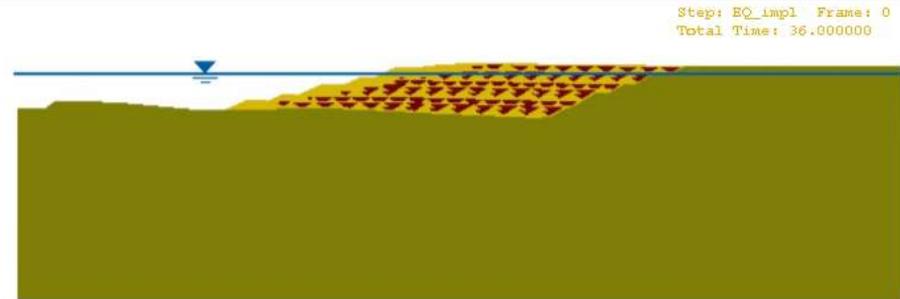
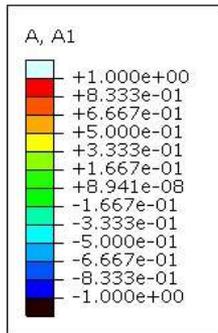


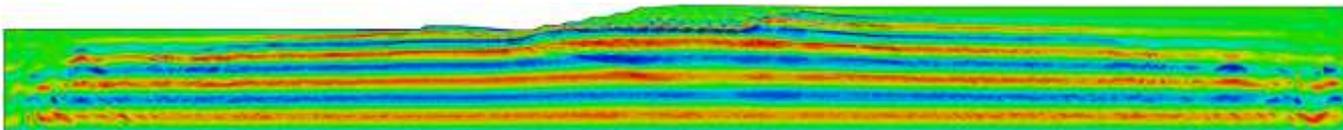
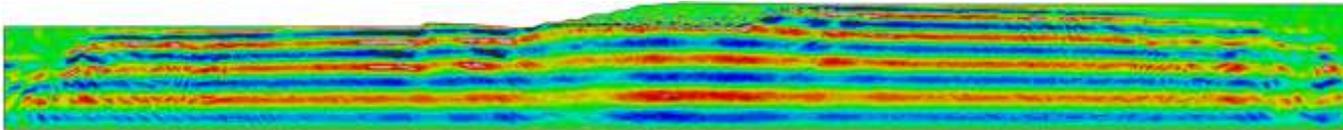
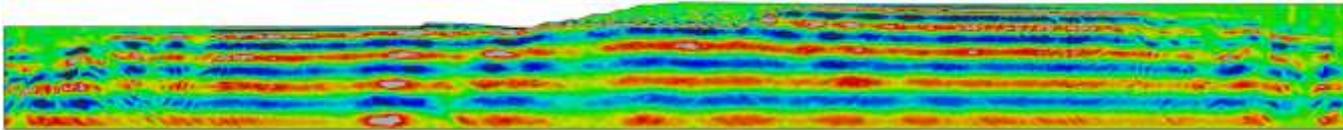
Step: EQ_impl Frame: 0
Total Time: 36.000000



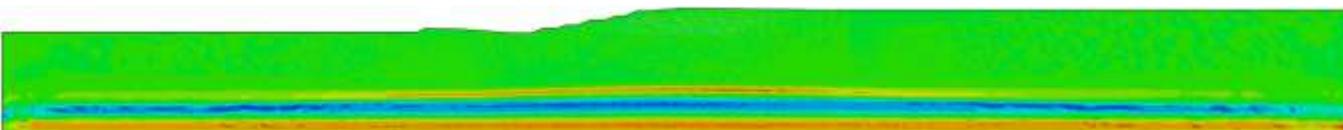
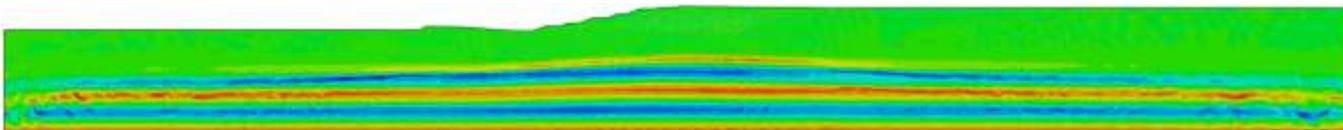
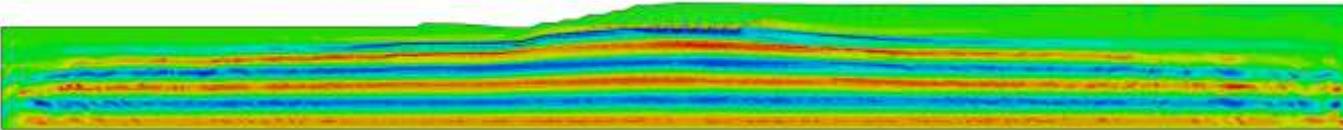
Deformations of a residual lake slope under a 2500-years recurrence seismic excitation: FE-Simulations

Slope with a soil profile consisting of clayey partitions and sandy material)



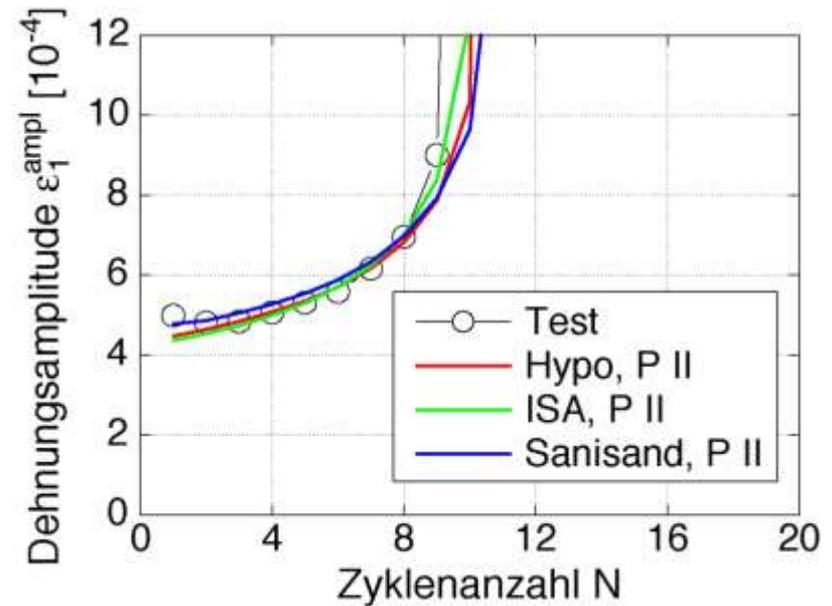
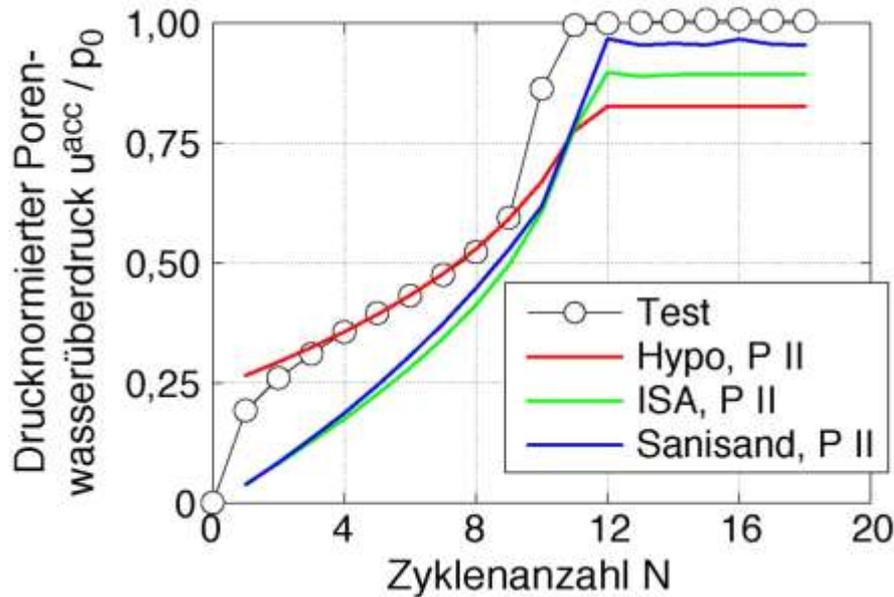


Thank you very much for your attention!



Simulationen: Zyklische Belastung

UndrÄnierte Bedingungen, isotrope Anfangsspannung,
Spannungszyklen, mitteldichte Lagerung ($I_{D0} = 0,67$)

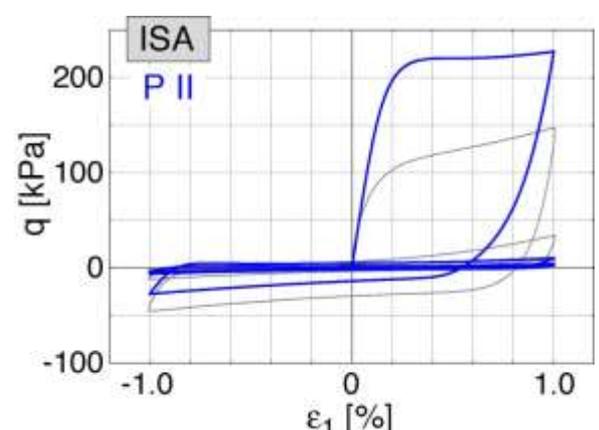
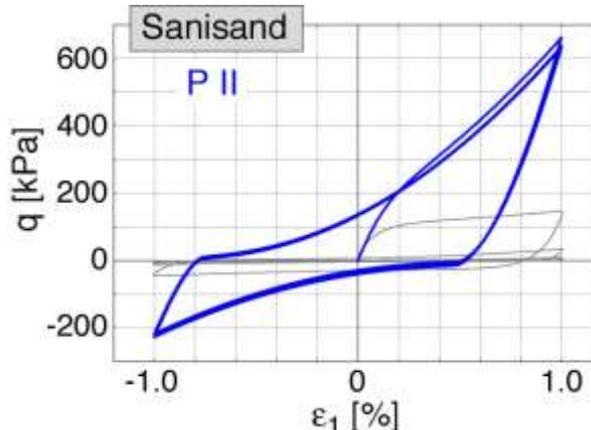
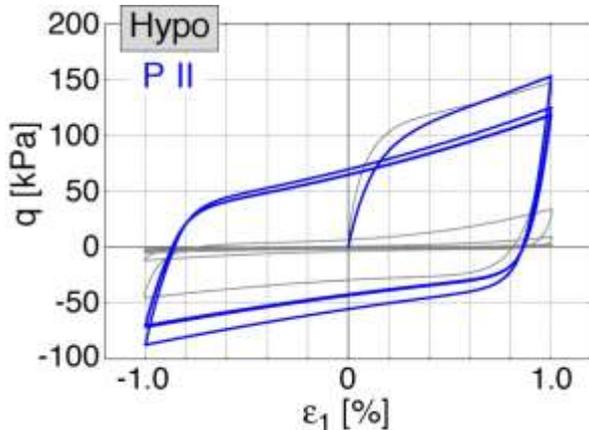
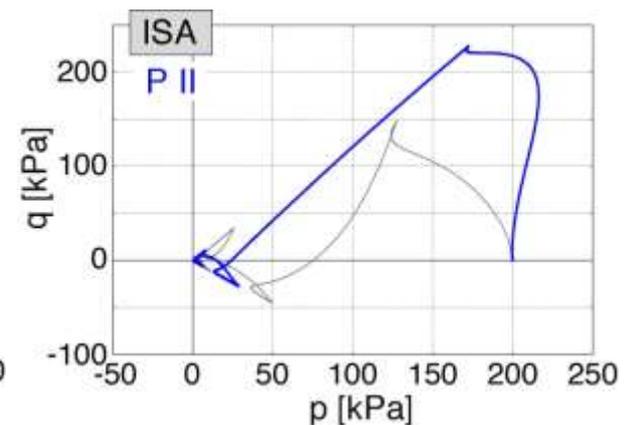
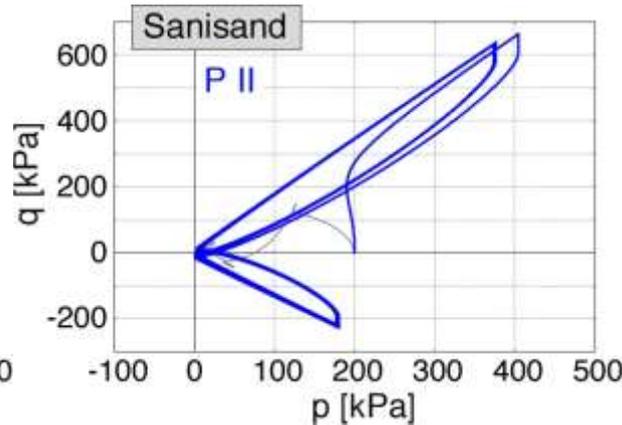
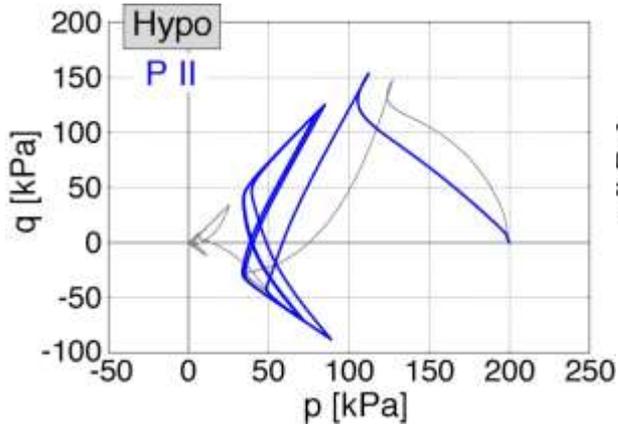


→ gute Reproduktion der gemessenen Relaxation der effektiven Spannung (= Porenwasserdruckanstieg) und der Amplitude der axialen Dehnung ϵ_1^{ampl} , d.h. Steifigkeit in den Zyklen

Simulationen: Zyklische Belastung

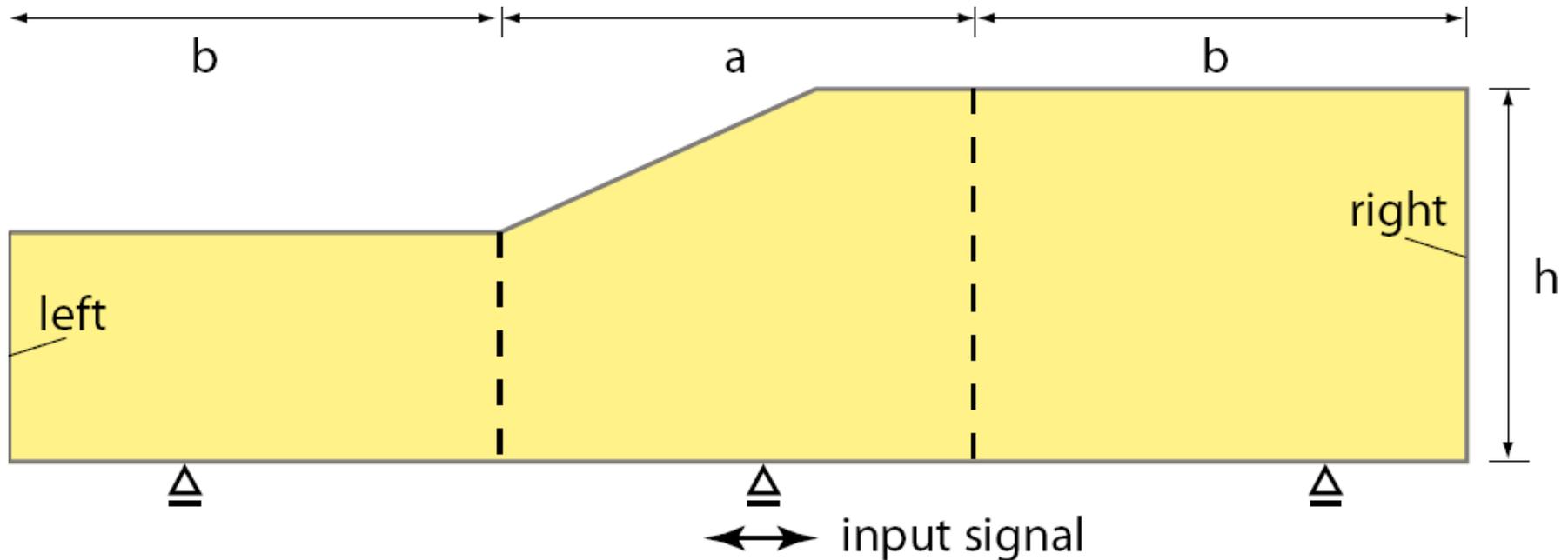
Undrained conditions, isotropic initial stress,

Dehnungszyklen mit relativ großer Amplitude $\varepsilon_1^{ampl} = 1 \cdot 10^{-2}$, **mitteldicht** ($I_{D0} = 0,66$)



→ Versuch endet bei $p = q = 0$, Modellprognosen in achtförmigem Pfad (Hypo) bzw. großem (Sanisand) oder sehr kleinem (ISA) „Schmetterling“

Wahl der Modellgröße



Auf welche Kriterien ist bei der Modellgröße zu achten?

- Simulationszeit $t_s <$ Reflexionszeit t_r einer Welle bis zum Zentrum des Gebietes:
- $t_r = (h + a/2 + 2b)/c$, wobei c die Wellengeschwindigkeit ist
- Bei nicht linearen Stoffbeziehungen mittlere Geschwindigkeit $c^* = h/t_h$ an einer Säule, bei der das gleiche Material betrachtet wird und die Welle die Zeit t_h braucht, damit sie die Oberfläche erreicht.

Simulationen: Zyklische Belastung

Entwicklung eines Parametersatzes für jedes Modell zur besseren Reproduktion der zyklischen Versuche

- Hypoplastizität mit intergranularer Dehnung:**

	φ_c [°]	e_{i0}	e_{c0}	e_{d0}	h_s [MPa]	n	α	β	R	m_R	m_T	β_R	χ
I	33,1	1,212	1,054	0,677	4000	0,27	0,14	2,5	10^{-4}	5	2	0,5	6
II										2,2	1,1	0,1	5,5

- Sanisand:**

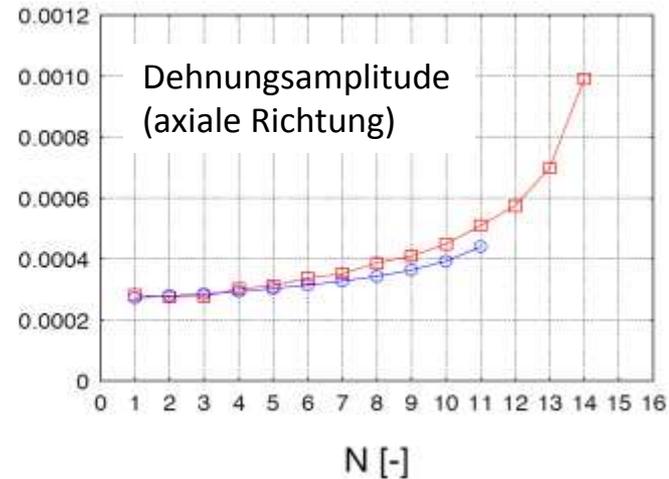
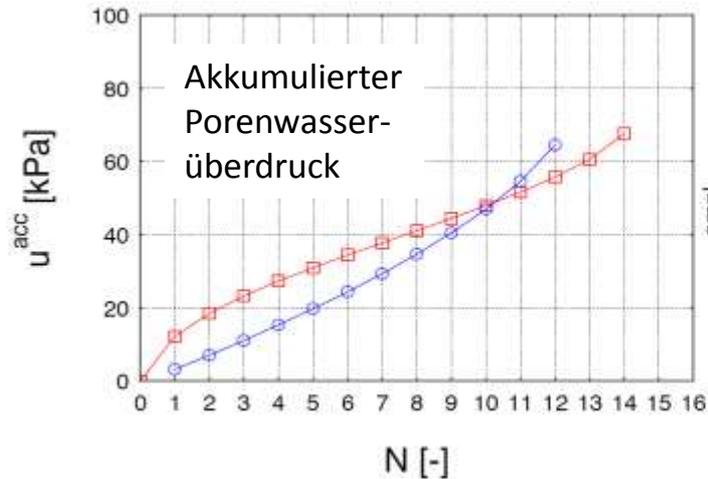
	e_0	λ	ζ	M_c	M_e	m	G_0	ν	h_0	c_h	n_b	A_0	n_d	z_{max}	c_z
I	1,103	0,122	0,205	1,34	0,94	0,05	100	0,25	4,0	0,95	1,2	0,9	2,0	1,0	100
II							130		20	0,70				20	5000

- ISA:**

	e_{i0}	...	f_{b0}	R	m_R	β	χ_h	c_z	r_F
I	1,21	...	1,8	10^{-4}	5,0	1,0	7,0	5000	1,6
II					1,7	0,1	11,0	50000	

Kalibration der Parameter anhand eines undränierten zyklischen Versuches am Sand Inden 6F1 mit lockerer Lagerung ($I_{D0} = 0,27$)

ISA-Modell (optimaler Parametersatz)



Rot = Versuch
Blau = Rechnung

